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A Note on Nearly Quasi-Einstein Manifolds

SHYAMAL KUMAR HUI

Nikhil Banga Sikshan Mahavidyalya, Bishnupur, Bankura - 722 122, West Bengal, India

Abstract. The object of the present paper is to study nearly quasi-Einstein manifold. Also we have studied decomposable Riemannian manifold and it is shown that a decomposable Riemannian manifold is nearly quasi-Einstein if and only if both the decompositions are Einstein.

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1. Introduction

It is well known that a Riemannian manifold $(M^n, g)(n > 2)$ is Einstein if its Ricci tensor S of type (0,2) is of the form $S = \alpha g$, where α is a constant, which reduces to $S = \frac{r}{n}g$, r being the scalar curvature (constant) of the manifold.

The notion of quasi-Einstein manifolds arose during the study of exact solutions of the Einstein field equations as well as during considerations of quasi-umbilical hypersurfaces. For instance, the Robertson-Walker spacetimes are quasi-Einstein manifolds. A non-flat Riemannian manifold $(M^n, g)(n > 2)$ is said to be quasi-Einstein manifold [1, 3, 5, 6, 7, 8, 9, 10, 11, 12, 15, 16] if its Ricci tensor S of type (0,2) is not identically zero and satisfies the following:

$$S(X,Y) = \alpha g(X,Y) + \beta A(X)A(Y), \tag{1}$$

where α , β are scalars of which $\beta \neq 0$ and A is a nowhere vanishing 1-form defined by $g(X,\rho) = A(X)$ for all X; ρ being a unit vector field, called the generator of the manifold. Such an n-dimensional quasi-Einstein manifold is denoted by $(QE)_n$. The scalars α , β are known as the associated scalars of the manifold. Also the 1-form A is called the associated 1-form of the manifold. From the above definition it follows that every Einstein manifold is quasi-Einstein. In particular, every Ricci-flat (e.g. Schwarzschild spacetime) manifold is quasi-Einstein.

Recently the notion of quasi-Einstein manifold have been weakened by De and Gaji [2, 14] and they introduced the notion of nearly quasi-Einstein manifold with the existence of such

Email address: shyamal_hui@yahoo.co.in

notion. A Riemannian manifold $(M^n, g)(n > 2)$ is called *nearly quasi-Einstein* if its Ricci tensor S is not identically zero and satisfies the condition

$$S(X,Y) = \alpha g(X,Y) + \beta D(X,Y), \tag{2}$$

where α , β are non-zero scalars and D is a symmetric non-zero (0, 2) tensor. The scalars α , β are known as associated scalars and D is called the associated tensor of the manifold. Such an n-dimensional manifold is denoted by $N(QE)_n$.

The present paper deals with a study of $N(QE)_n(n > 2)$. The paper is organized as follows. Section 2 is concerned with Ricci-pseudosymmetric $N(QE)_n$ and we obtain a $N(QE)_n$ is Ricci-pseudosymmetric if and only if it is D-pseudosymmetric. Section 4 deals with decomposable Riemannian manifold. It is proved that a decomposable Riemannian manifold is nearly quasi-Einstein if and only if both the decompositions are Einstein. Section 5 deals with some global properties of $N(QE)_n$ and it is proved that under certain condition such a manifold does not admit non-zero Killing vector field, non-zero projective Killing vector field and non-zero conformal Killing vector field. Finally the last section deals with an interesting example of nearly quasi-Einstein manifold with non-vanishing scalar curvature which is not quasi-Einstein.

2. Ricci-pseudosymmetry $N(QE)_n$

An *n*-dimensional Riemannian manifold (M^n, g) is called Ricci-pseudosymmetric [4] if the tensor $R \cdot S$ and Q(g, S) are linearly dependent, where

$$(R(X,Y) \cdot S)(Z,U) = -S(R(X,Y)Z,U) - S(Z,R(X,Y)U), \tag{3}$$

$$Q(g,S)(Z,U;X,Y) = -S((X \wedge_g Y)Z,U) - S(Z,(X \wedge_g Y)U). \tag{4}$$

Thus the condition of Ricci-pseudosymmetry is

$$(R(X,Y)\cdot S)(Z,U) = L_S Q(g,S)(Z,U;X,Y)$$
(5)

holding on the set $U_S = \{x \in M : S \neq \frac{r}{n}g \text{ at } x\}$, where L_S is some function on U_S . If $R \cdot S = 0$ then M is called Ricci-semisymmetric. Every Ricci-semisymmetric manifold is Ricci-pseudosymmetric but the converse is not true [4]. In [2] De and Gaji studied Ricci-semisymmetric $N(QE)_n$.

Now we prove the following:

Theorem 1. A nearly quasi-Einstein manifold is Ricci-pseudosymmetric if and only if it is D-pseudosymmetric.

Proof. We now consider a Ricci-pseudosymmetric $N(QE)_n$. Then from (3)–(5), we can write

$$S(R(X,Y)Z,U) + S(Z,R(X,Y)U) = L_S\{S(X,U)g(Y,Z) - S(Y,U)g(X,Z) + S(X,Z)g(Y,U) - S(Y,Z)g(X,U)\}.$$
(6)

Using (2) in (6), we get

$$D(R(X,Y)Z,U) + D(Z,R(X,Y)U) = L_S\{D(X,U)g(Y,Z) - D(Y,U)g(X,Z) + D(X,Z)g(Y,U) - D(Y,Z)g(X,U)\},$$
(7)

which implies that the manifold is *D*-pseudosymmetric.

Conversely, if the manifold is *D*-pseudosymmetric, then (7) holds. By virue of (2), it follows from (7), we get the relation(6) and consequently, the manifold is Ricci-pseudosymmetric.

Corollary 1. A nearly quasi-Einstein manifold is Ricci-semisymmetric if and only if it is D-semisymmetric [2].

3. Decomposable Riemannian manifold

A non-flat Riemannian manifold (M^n, g) is said to be decomposable [19] if it can be expressed as $M_1^p \times M_2^{n-p}$ for $2 \le p \le n-2$, that is, in some coordinate neighbourhood of the Riemannian manifold (M^n, g) , the metric can be expressed as

$$ds^2 = g_{ij}dx^i dx^j = \tilde{g}_{ab}dx^a dx^b + \tilde{g}_{a\beta}^* dx^a dx^\beta, \tag{8}$$

where \tilde{g}_{ab} are functions of $x^1, x^2, \cdots, x^p (p < n)$ denoted by \tilde{x} and $\tilde{g}_{\alpha\beta}$ are functions of $x^{p+1}, x^{p+2}, \cdots, x^n$ denoted by \tilde{x} ; a, b, c, \cdots run from 1 to p and $\alpha, \beta, \gamma, \cdots$ run from p+1 to n. The two parts of (8) are the metrics of $M_1^p (p \ge 2)$ and $M_2^{n-p} (n-p \ge 2)$ which are called the decomposition of the manifold $M^n = M_1^p \times M_2^{n-p} (2 \le p \le n-2)$.

Let (M^n, g) be a Riemannian manifold such that $M_1^p \times M_2^{n-p}$ for $2 \le p \le n-2$. Here throughout this section each object denoted by a "tilde" is assumed to be from M_1 and each object denoted by a "star" is assumed to be from M_2 .

Let \tilde{X} , \tilde{Y} , \tilde{Z} , \tilde{U} , $\tilde{V} \in \chi(M_1)$ and $\overset{*}{X}$, $\overset{*}{Y}$, $\overset{*}{Z}$, $\overset{*}{U}$, $\overset{*}{V} \in \chi(M_2)$, then we have the following relations:

$$R(\tilde{X}, \tilde{Y}, \tilde{Z}, \tilde{U}) = 0 = R(\tilde{X}, \overset{*}{Y}, \tilde{Z}, \overset{*}{U}) = R(\tilde{X}, \overset{*}{Y}, \overset{*}{Z}, \overset{*}{U}),$$

$$(\nabla_{\overset{*}{X}}R)(\tilde{Y}, \tilde{Z}, \tilde{U}, \tilde{V}) = 0 = (\nabla_{\tilde{X}}R)(\tilde{Y}, \overset{*}{Z}, \tilde{U}, \overset{*}{V}) = (\nabla_{\overset{*}{X}}R)(\tilde{Y}, \overset{*}{Z}, \tilde{U}, \overset{*}{V}),$$

$$R(\tilde{X}, \tilde{Y}, \tilde{Z}, \tilde{U}) = \tilde{R}(\tilde{X}, \tilde{Y}, \tilde{Z}, \tilde{U}); R(\overset{*}{X}, \overset{*}{Y}, \overset{*}{Z}, \overset{*}{U}) = \overset{*}{R}(\overset{*}{X}, \overset{*}{Y}, \overset{*}{Z}, \overset{*}{U}),$$

$$S(\tilde{X}, \tilde{Y}) = \tilde{S}(\tilde{X}, \tilde{Y}); S(\overset{*}{X}, \overset{*}{Y}) = \overset{*}{S}(\overset{*}{X}, \overset{*}{Y}),$$

$$(\nabla_{\tilde{X}}S)(\tilde{Y}, \tilde{Z}) = (\tilde{\nabla}_{\tilde{X}}S)(\tilde{Y}, \tilde{Z}); (\nabla_{\overset{*}{X}}S)(\overset{*}{Y}, \overset{*}{Z}) = (\overset{*}{\nabla}_{\overset{*}{X}}S)(\overset{*}{Y}, \overset{*}{Z}),$$
and $r = \tilde{r} + \overset{*}{r},$

where r, \tilde{r} , and \tilde{r} are the scalar curvature of M, M_1 , M_2 respectively.

In [19] Yano and Kon find a necessary and sufficient condition that both the decompositions of a decomposable Riemannian manifold are Einstein and they obtained that **Theorem 2.** In a decomposable Riemannian manifold $M^n = M_1^p \times M_2^{n-p} (2 \le p \le n-2)$, a necessary and sufficient condition that the two decompositions are both Einstein is that the Ricci tensor of the manifold has the form

$$S(X,Y) = ag(X,Y) + bF(X,Y), \tag{9}$$

a and b being necessarily constant and F is a (0, 2) type metric tensor such that

$$F(X,Y) = \tilde{g}(\tilde{X},\tilde{Y}) + \tilde{g}(\tilde{X},\tilde{Y}). \tag{10}$$

By virtue of Theorem 2, we can state the following:

Theorem 3. A decomposable Riemannian manifold $M^n = M_1^p \times M_2^{n-p} (2 \le p \le n-2)$ is nearly quasi-Einstein if and only if both the decompositions are Einstein.

4. Some global properties of $N(QE)_n$

This section is concerned with a compact, orientable $N(QE)_n(n > 2)$ without boundary with α , β as associated scalars and D as the structure tensor. Then we prove the following:

Theorem 4. If in a compact, orientable $N(QE)_n(n > 2)$ without boundary, the associated scalars and the structure tensor are such that $\alpha < 0$ and $\beta D(X,X) < 0$, then there exists no non-zero Killing vector field in this manifold.

Proof. It is known that [17] for a vector field X in a Riemannian manifold M, the following relation holds

$$\int_{M} \left[S(X,X) - |\nabla X|^{2} - (divX)^{2} \right] dv \le 0, \tag{11}$$

where "dv" denotes the volume element of M. If X is a Killing vector field, then div X = 0 [18]. Hence (11) takes the following form

$$\int_{M} \left[S(X,X) - |\nabla X|^{2} \right] d\nu = 0. \tag{12}$$

Let us consider $\alpha < 0$ and $\beta D(X,X) < 0$. Hence by virtue of (2) we have

$$\int_{M=N(QE)_n} \left[\alpha |X|^2 + \beta D(X,X) - |\nabla X|^2 \right] d\nu$$

$$\geq \int_M \left[S(X,X) - |\nabla X|^2 \right] d\nu,$$

which yields by virtue of (12) that

$$\int_{M} \left[\alpha |X|^{2} + \beta D(X, X) - |\nabla X|^{2} \right] d\nu \ge 0.$$

If α < 0 and $\beta D(X,X)$ < 0, then the last relation reduces to

$$\int_{M} \left[\alpha |X|^{2} + \beta D(X,X) - |\nabla X|^{2} \right] d\nu = 0.$$

Hence X = 0. This proves the theorem.

Definition 1. [18] A vector field X in a Riemannian manifold (M^n, g) (n > 2) is said to be projective Killing vector field if it satisfies

$$(\$_X g)(Y, Z) = \omega(Y)Z + \omega(Z)Y$$

for any vector fields Y and Z, ω being a certain 1-form and \$\\$ is the operator of Lie differentiation.

Theorem 5. If in a compact, orientable $N(QE)_n(n > 2)$ without boundary, the associated scalars and the structure tensor are such that $\alpha \le 0$ and $\beta D(X,X) \le 0$, then a projective Killing vector field has vanishing covariant derivative, and if $\alpha < 0$ and $\beta D(X,X) < 0$, then there exists no non-zero projective Killing vector field in this manifold.

Proof. We know that [17] for a vector field X in a Riemannian manifold M, the following relation holds

$$\int_{M} \left[S(X,X) - \frac{1}{4} |d\xi|^{2} - \frac{n-1}{2(n+1)} (divX)^{2} \right] dv = 0, \tag{13}$$

where ξ is an 1-form corresponding to the vector field X. We now assume $\alpha \leq 0$ and $\beta D(X,X) \leq 0$. Therefore (13) yields $S(X,X) \leq 0$ and hence from (13) we obtain $d\xi = 0$ and div X = 0. This implies that X is harmonic as well as a Killing vector field. Consequently its covariant derivative vanishes. This proves the theorem.

Definition 2. [18] A vector field X in a Riemannian manifold (M^n, g) (n > 2) is said to be conformal Killing vector field if it satisfies

$$\$_X g = 2\rho g$$

for any vector field X, where ρ is given by $\rho = -\frac{1}{n}(\operatorname{div} X)$ and \$ is the operator of Lie differentiation.

Theorem 6. If in a compact, orientable $N(QE)_n(n > 2)$ without boundary, the associated scalars and the structure tensor are such that $\alpha < 0$ and $\beta D(X,X) < 0$, then there exists no non-zero conformal Killing vector field in this manifold.

Proof. It is known from [17] that for a vector field X in a Riemannian manifold M, the following relation holds

$$\int_{M} \left[S(X,X) - |\nabla X|^{2} - \frac{n-2}{n} (divX)^{2} \right] dv = 0, \tag{14}$$

where dv denotes the volume element of M. Now we assume that the associated scalars and the structure tensor are such that $\alpha < 0$ and $\beta D(X,X) < 0$. Then proceeding similarly as before we obtain

$$\nabla X = 0$$
, $div X = 0$.

This proves the theorem.

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5. Example of $N(QE)_n$

We define a Riemannian metric g on the n-dimensional real number space \mathbb{R}^n by the formula

$$ds^{2} = e^{kx^{1}} [(dx^{1})^{2} + \sin^{2} x^{3} (dx^{2})^{2} + (dx^{3})^{2}] + f(x^{4})(dx^{4})^{2} + \sum_{l=5}^{n} (dx^{l})^{2},$$
 (15)

where x^1 is non-zero finite, $0 < x^3 < \frac{\pi}{2}$, k is a non-zero finite real number excepting ± 2 and f is a positive smooth function of x^4 only. Then the only non-vanishing components of the Christoffel symbols, the curvature tensor, the Ricci tensors are given by

$$\begin{split} \Gamma_{11}^1 &= \frac{k}{2} = \Gamma_{12}^2 = \Gamma_{13}^3 = -\Gamma_{33}^1, \Gamma_{22}^1 = -\frac{k}{2} \sin^2 x^3, \\ \Gamma_{22}^3 &= -\sin x^3 \cos x^3, \Gamma_{23}^2 = \cot x^3, \Gamma_{44}^4 = \frac{1}{2} \frac{f'(x^4)}{f(x^4)}, \\ R_{2332} &= \left(\frac{k^2}{4} - 1\right) e^{kx^1} \sin^2 x^3, S_{22} = \left(\frac{k^2}{4} - 1\right) \sin^2 x^3, S_{33} = \left(\frac{k^2}{4} - 1\right). \end{split}$$

Here the scalar curvature of the manifold is $r = 2(\frac{k^2}{4} - 1)e^{-kx^1} \neq 0$. Therefore \mathbb{R}^n with the considered metric is a Rimennian manifold (M^n, g) of non-vanishing scalar curvature. We shall now show that this M^n is a nearly quasi-Einstein manifold, i.e., it satisfies (2).

Let us now consider the associated scalars and the components of the structure tensor of *D* as follows:

$$\alpha = \frac{1}{2} \left(\frac{k^2}{4} - 1 \right) e^{-kx^1}, \ \beta = \frac{1}{2} \left(\frac{k^2}{4} - 1 \right), \tag{16}$$

and

$$D_{ij}(x) = \begin{cases} \sin^2 x^3 & \text{for } i, j = 2, 2, \\ 1 & \text{for } i, j = 3, 3, \\ 0 & \text{otherwise} \end{cases}$$
 (17)

at any point $x \in M$.

Then it can be easily shown that the manifold under consideration is nearly quasi-Einstein manifold. Hence we can state the following:

Theorem 7. Let (M^n, g) be a Riemannian manifold endowed with the metric given in (15). Then (M^n, g) is a nearly quasi-Einstein manifold with non-vanishing scalar curvature, which is not quasi-Einstein.

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