



## A common best proximity point theorem for $\phi$ -dominated pair

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**Abstract.** In the present research, an interesting common best proximity point theorem for pairs of non-self-mappings is presented. It satisfies a weakly contraction-like condition, thereby producing common optimal approximate solutions of certain simultaneous fixed point equations.

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### 1. Introduction

Fixed point theory is indispensable  $Tx = x$  for self-mappings  $T$  on subsets of metric space or normed space. Let  $A$  and  $B$  be non-empty subsets of metric space  $(X, d)$  and let  $T : A \rightarrow B$  be non-self mapping. If the equation  $Tx = x$  does not possess solution, then  $d(x, Tx) > 0$ . In this case, it is important that we find an element  $x \in A$  such that  $d(x, Tx)$  is minimum in some sense. For example, the best approximation problem and best proximity problem are investigated in this regard (see [2] and [5]). An element  $x \in A$  is said to be a best proximity point of  $T$  if  $d(x, Tx) = d(A, B)$  where

$$d(A, B) = \inf\{d(x, y) : x \in A, y \in B\}.$$

It is easy to check that if  $T$  is self-mapping the best proximity problem reduces to fixed point problem. There are several various of contractions that guarantee the existence of a best proximity point (see [2], [5], and [11]).

Suppose that  $A$  and  $B$  be nonempty subsets of metric space  $(X, d)$ . Let  $T : A \rightarrow B$  and  $S : A \rightarrow B$  be nonself mapping. Let considering the fact  $S$  and  $T$  are nonself-mappings, it is possible that the equations  $Tx = x$  and  $Sx = x$  have a common solution, considered as a common fixed point of the mappings  $T$  and  $S$ . When the equations have no common solution, one thinks to find an element  $x$  that is in near proximity to

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$Tx$  and  $Sx$  in the sense that  $d(x, Tx)$  and  $d(x, Sx)$  are minimal. In fact, one investigates the existence of such optimal approximate solutions, known as common best proximity points, to the equations  $Sx = x$  and  $Tx = x$ . Further, one can comprehend that the real valued functions  $x \rightarrow d(x, Tx)$  and  $x \rightarrow d(x, Sx)$  approximate the value of the error of proximate solution of the equations  $Tx = x$  and  $Sx = x$ . In view of the fact that  $d(A, B) \leq d(x, Tx)$  and  $d(A, B) \leq d(x, Sx)$ , a common best proximity point theorem determines global minimum of both functions  $x \rightarrow d(x, Tx)$  and  $x \rightarrow d(x, Sx)$  by limiting a common approximate solution of the equations  $Tx = x$  and  $Sx = x$  to attain the requirement that  $d(x, Sx) = d(A, B)$  and  $d(x, Tx) = d(A, B)$ .

Common best proximity point problem was studied by many mathematicians (see [7], [8] and [11]).

## 2. Preliminary Concepts

**Definition 1.** An element  $x \in X$  is said to be common best proximity point of the non-self-mappings  $S : A \rightarrow B$  and  $T : A \rightarrow B$  if it satisfies the condition that

$$d(x, Sx) = d(x, Tx) = d(A, B).$$

**Definition 2.** [4] A function  $\phi : [0, +\infty) \rightarrow [0, +\infty)$  is called a comparison if it satisfies the following conditions:

- $\phi$  is increasing,
- the sequence  $(\phi^n(t))_{n \in \mathbb{N}}$  converges to 0 as  $n \rightarrow +\infty$ , for all  $t \in [0, +\infty)$ .

We recall that a self-mapping  $T$  on a metric space  $(X, d)$  is said to be  $\phi$ -contraction if

$$d(T(x), T(y)) \leq \phi(d(x, y))$$

for any  $x, y \in X$ ; where  $\phi$  is comparison function.

**Remark 1.** If  $\phi$  is comparison function then

- $\phi(t) < t$  for any  $t \in (0, +\infty)$ ,
- $\phi(t) = 0$  if and only if  $t = 0$ .

**Lemma 1.** [4] Let  $(X, d)$  be a metric space and let  $(x_n)_{n \in \mathbb{N}}$  be a sequence in  $X$  such that  $d(x_{n+1}, x_n) \rightarrow 0$ . If  $(x_n)_{n \in \mathbb{N}}$  is not Cauchy sequence then there exists  $\epsilon > 0$  and sequences  $(n(k))$  and  $(m(k))$  of positive integers such that the following sequences tend to  $\epsilon$  as  $k \rightarrow +\infty$ :

$$\begin{aligned} & d(x_{m(k)}, x_{n(k)}), \quad d(x_{m(k)}, x_{n(k)+1}), \quad d(x_{m(k)-1}, x_{n(k)}), \\ & d(x_{m(k)-1}, x_{n(k)+1}), \quad d(x_{m(k)+1}, x_{n(k)+1}), \quad d(x_{m(k)+1}, x_{n(k)}). \end{aligned}$$

**Definition 3.** Let  $S : A \rightarrow B$ ,  $T : A \rightarrow B$  and  $F : B \rightarrow A$  be given.  $F$  is said to commute with the pair  $(S, T)$  if  $SFT = TFS$ .

**Definition 4.** Let  $S : A \longrightarrow B$ ,  $T : A \longrightarrow B$ ,  $F : B \longrightarrow A$  and  $G : B \longrightarrow A$  be mappings. The pair  $(F, S)$  is said to be  $\phi$ -dominated by the pair  $(G, T)$  if for any  $x \in A$  and  $y \in B$  it satisfies the condition that

$$d(FSx, FSy) \leq \phi(d(GTx, GTy))$$

where  $\phi$  is comparison function.

### 3. Main Results

From here throughout this paper,  $X$  denotes a complete metric space and  $A$  and  $B$  are its nonempty subsets.

Now, we are ready to present our main result.

**Theorem 1.** Let  $A$  and  $B$  be closed. Moreover, assume that  $S : A \longrightarrow B$ ,  $T : A \longrightarrow B$ ,  $F : B \longrightarrow A$  and  $G : B \longrightarrow A$  are continuous functions satisfying the following conditions:

- (1)  $FS$  commutes with  $GT$  and  $SF$  commutes with  $TG$ .
- (2)  $(F, S)$  is  $\phi$ -dominated by  $(G, T)$  and  $(S, F)$  is  $\psi$ -dominated by  $(T, G)$ , where  $\phi$  and  $\psi$  are comparison functions.
- (3)  $FS(A) \subset GT(A)$  and  $SF(B) \subset TG(B)$ .
- (4)  $S$  and  $T$  commute with the pair  $(F, G)$ , and  $F$  and  $G$  commute with the pair  $(S, T)$ .
- (5) There is a non-negative number  $\alpha < 1$  such that for all  $x \in A$

$$d(Sx, FSx) \leq \alpha d(Tx, GTx) + (1 - \alpha)d(A, B).$$

Then, there exists  $u \in A$  and  $v \in B$  such that

$$d(u, Su) = d(u, Tu) = d(A, B)$$

$$d(v, Fv) = d(v, Gv) = d(A, B)$$

$$d(u, v) = d(A, B).$$

If  $(I, S)$  is  $\phi$ -dominated by  $(I, T)$ , where  $I$  is the identity mapping on  $B$ , then

$$2d(A, B) + \phi(2d(A, B) + d(a, a')) - d(a, a') \geq 0$$

whenever  $a'$  is another common best proximity point of  $S$  and  $T$ .

*Proof.* Let  $x_0$  be an element in  $A$ . Since  $FS(A) \subset GT(A)$ , there exists an element  $x_1 \in A$  such that  $FS(x_0) = GT(x_1)$ . Again by  $FS(A) \subset GT(A)$ , we can choose an element  $x_2 \in A$  such that  $FS(x_1) = GT(x_2)$ . By continuing this process, we can construct a sequence  $(x_n)$  such that  $FS(x_n) = GT(x_{n+1})$ . By condition (2) there exists continuous non-decreasing function  $\phi : [0, +\infty) \longrightarrow [0, +\infty)$ , with  $\lim_{n \rightarrow \infty} \phi_n(t) = 0$  for all  $t \in [0, +\infty)$ , such that

$$d(FSx_n, FSx_{n+1}) \leq \phi(d(GTx_n, GTx_{n+1})).$$

Since  $FS(x_n) = GT(x_{n+1})$  so,

$$\begin{aligned} d(FSx_n, FSx_{n+1}) &\leq \phi(d(GTx_n, GTx_{n+1})) = \phi(d(FSx_{n-1}, FSx_n)) \\ &\leq \phi^2(d(GTx_{n-1}, GTx_n)) = \phi^2(d(FSx_{n-2}, GTx_{n-1})) \\ &\leq \phi^3(d(FSx_{n-3}, FSx_{n-2})) \\ &\leq \dots \leq \phi^n(d(FSx_0, FSx_1)). \end{aligned}$$

Hence,

$$d(FSx_n, FSx_{n+1}) \leq \phi^n(d(FSx_0, FSx_1))$$

taking  $n \rightarrow +\infty$  we have

$$\lim_{n \rightarrow +\infty} d(FSx_n, FSx_{n+1}) = 0.$$

**Clime:**  $(FSx_n)$  is a Cauchy sequence.

Let  $(FSx_n)$  is not Cauchy. Then there exists  $\epsilon > 0$  and two sequences  $(n(k))$  and  $(m(k))$  of positive integers such that

$$n(k) > m(k) > k, d(FSx_{m(k)}, FSx_{n(k)-1}) < \epsilon \text{ and } d(FSx_{m(k)}, FSx_{n(k)}) \geq \epsilon. \quad (1)$$

Using condition (2) and the fact that  $\phi$  is a comparison function we obtain that

$$d(FSx_{m(k)+1}, FSx_{n(k)}) \leq \phi(d(GTx_{m(k)+1}, GTx_{n(k)})) = \phi(d(FSx_{m(k)}, FSx_{n(k)-1})) \leq \phi(\epsilon) < \epsilon. \quad (2)$$

Taking  $n \rightarrow +\infty$  in (2) we get

$$\epsilon = \lim_{k \rightarrow +\infty} d(FSx_{m(k)+1}, FSx_{n(k)}) \leq \phi(\epsilon) < \epsilon.$$

This is a contradiction. Hence  $(FSx_n)$  is Cauchy sequence. Obviously,  $(GTx_n)$  is also Cauchy. Because of the completeness of the space, there exists an element  $x \in A$  such that  $FSx_n \rightarrow x$ . By continuity of  $FS$  and  $GT$ ;

$$\begin{aligned} (GT)(FS)x_n &\rightarrow GTx \\ (FS)(GT)x_n &\rightarrow FSx. \end{aligned}$$

By condition (1), it follows that  $GTx = FSx$ . Put  $a = GTx = FSx$ . Then, by condition (1) and (2),

$$\begin{aligned} d(FSa, a) &= d(FSa, FSx) \\ &\leq \phi(d(GTa, GTx)) = \phi(d(GT(FSx), a)) \\ &= \phi(d(FS(GTx), a)) = \phi(d(FSa, a)). \end{aligned}$$

Since  $\phi$  is comparison by Remark 1 we get

$$d(FSa, a) = 0 \implies FSa = a.$$

Further,  $GTa = (GT)(FSx) = (FS)(GTx) = FSa = a$ . A similar argument can be given to assert that there exists an element  $b \in B$  such that  $SFb = TGb = b$ . Also, since  $T$  commutes with the pair  $(F, G)$ ,  $GTfb = FTGb = Fb$ . So,

$$d(a, Fb) = d(FSa, FS(Fb)) \leq \phi(d(GTa, GT(Fb))) = \phi(d(a, Fb)).$$

Since  $\phi$  is a comparison by Remark 1, it follows that  $Fb = a$ . By the same argument we can show that  $Gb = a$ ,  $Sa = b$  and  $Ta = b$ . Consequently, by condition (5) there exists  $\alpha \in [0, 1)$  such that

$$d(a, b) = d(Sa, FSa) \leq \alpha d(Ta, GTa) + (1 - \alpha)d(A, B) = \alpha d(a, b) + (1 - \alpha)d(A, B).$$

So  $d(a, b) \leq d(A, B)$  and hence

$$d(a, b) = d(A, B).$$

Therefore,

$$d(a, Sa) = d(a, Ta) = d(a, b) = d(A, B)$$

$$d(b, Fb) = d(b, Gb) = d(a, b) = d(A, B).$$

If  $(I, S)$  is  $\phi$ -dominated by  $(I, T)$  and  $a'$  is another common best proximity point of  $S$  and  $T$ , then

$$\begin{aligned} d(a, a') &\leq d(a, Sa) + d(Sa, Sa') + d(a', Sa') \\ &\leq 2d(A, B) + \phi(d(Ta, Ta')) \\ &\leq 2d(A, B) + \phi(2d(A, B) + d(a, a')) \end{aligned}$$

and hence

$$2d(A, B) + \phi(2d(A, B) + d(a, a')) - d(a, a') \geq 0.$$

**Example 1.** Consider the space of real numbers with the Euclidean metric. Let  $A = [3, +\infty)$  and  $B = (-\infty, -3]$  Suppose that  $S, T : A \rightarrow B$ ,  $F, G : B \rightarrow A$  and  $\phi, \psi : [0, +\infty) \rightarrow [0, +\infty)$  are defined by

$$S(x) = -3; \quad T(x) = -x; \quad F(y) = \begin{cases} 3 & y \in \mathbb{Z} \\ 4 & y \in \mathbb{R} \setminus \mathbb{Z} \end{cases}$$

$$; G(y) = -y \quad \text{and} \quad \phi(x) = \psi(x) = \frac{x}{1+x}.$$

It is easy to check that  $d(A, B) = 6$  and the mapping  $S, T, F$  and  $G$  are satisfied the conditions in Theorem 1 and

$$d(3, S(3)) = d(3, T(3)) = d(A, B)$$

$$d(-3, F(-3)) = d(-3, G(-3)) = d(A, B)$$

$$d(3, -3) = d(A, B).$$

If  $S$  and  $T$  are self-mappings on  $X$  and  $F$  and  $G$  are identity mappings on  $X$ , then Theorem 1 yields the following common fixed point theorem for pairs of commuting self-mappings.

**Corollary 1.** *Let  $X$  be a complete metric space. Moreover, assume that  $S : X \rightarrow X$ ,  $T : X \rightarrow X$  are continuous functions satisfying the following conditions:*

(1)  $S$  commutes with  $T$ .

(2) There exists comparison function  $\phi$  such that

$$d(Sx, Sy) \leq \phi(d(Tx, Ty)) \quad \text{for all } x, y \in X.$$

(3)  $S(X) \subset T(X)$ .

Then the pair  $(S, T)$  has a unique common fixed point.

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