EUROPEAN JOURNAL OF PURE AND APPLIED MATHEMATICS
Vol. 16, No. 2, 2023, 1024-1046
ISSN 1307-5543 - ejpam.com
Published by New York Business Global


# The generalization of integral transforms combined with He's polynomial 

Junaid Idrees Mustafa<br>Department of Mathematics, College of Education For Pure Sciences, University of Mosul, Mosul, Iraq


#### Abstract

Our goal in this paper is to generalize the integral transforms and use it with He's polynomial method to find the solution of the nonlinear partial differential equations. All results of theoretical studies regarding the generalization and its properties are presented. For the He's polynomial method, it is used to solve the nonlinear part of the partial differential equation. It is shown that the importance of my research is the combination of generalization of integral transforms with He's polynomial method allows for exact and approximate solutions configurations to be determined. Furthermore, the generalization of integral transforms has been shown to include most, or even all, of the integral transforms and be applicable to a variety of equations, making it a crucial tool in solving them. Finally, the capability of solutions to be obtained quickly and easily through this combined technique provides an invaluable tool for solving problems.


2020 Mathematics Subject Classifications: 35Q35, 44A05, 41A10, 41A58, 65D25, 65J15, 74H15.
Key Words and Phrases: Generalization of integral transform, He's polynomial method, nonlinear partial differential equations

## 1. Introduction

Integral transforms have become an important tool in mathematics in recent years and have been extensively studied by many researchers $[24,25,28]$. These transforms have been successfully applied to solve many linear equations, such as ordinary and partial differential equations (PDEs) and integral equations [17, 19, 20]. The utility of integral transforms is their ability to simplify the solution process, making it easier to calculate the solutions in a fraction of time. This has enabled the application of integral transforms to a wide variety of problems, allowing for the production of new solutions and the refinement of existing ones [18].

Furthermore, the development of integral transforms have allowed for the efficient computation of PDEs, opening up new possibilities in the production of exact and approximate solutions of the equations among them, PDEs [5, 23, 32]. Recently, various applications

DOI: https://doi.org/10.29020/nybg.ejpam.v16i2.4747
Email address: j.i.mustafa20@uomosul.edu.iq. (J.I. Mustafa)
of integral transforms have been found in different areas of engineering, mathematics and physics such as image processing, signal analysis and electric [21, 26, 30]. This is due to their properties and ability to transform a function from one domain to another domain while preserving important features of the function. Their use in these areas makes them a valuable tool as they provide efficient and accurate results. Consequently, integral transforms are being used more and more in applied mathematics [13, 15].

It is worth mentioning that the integral transforms can be used in combination with other methods to address the nonlinear parts of equations. This can provide a much more efficient solution, and can be used to analyse many different systems with greater accuracy [7, 29, 32].

One of these methods is He's polynomial, it is a reliable numerical approach for solving nonlinear PDEs. This method is based on the idea that a nonlinear PDE can be approximated by a polynomial in a certain variable. It works by expanding the nonlinear function into a set of truncated series of polynomials [6, 10]. This set of polynomials is then used to approximate the solution of the PDE. He's polynomial method is computationally efficient, since it only requires the evaluation of a few polynomial coefficients rather than a full numerical solution [9]. It has been used in a wide range of problems in fields such as fluid dynamics, astrophysics, and acoustics, and it is a powerful tool for solving nonlinear PDEs [27].

By understanding the underlying principles of integral transforms, it may become possible to develop more efficient and accurate methods for solving equations [1, 4, 8, 14, 16]. In this paper, the integral transforms are generalized, and then combined it with He's polynomial method to solve nonlinear PDEs. As the examples, we apply the combination of generalization (GN) of integral transforms and He's polynomial method to solve the nonlinear PDEs, which include the nonlinear gas dynamic equation, system of coupled nonlinear Burgers' equation and the non-homogeneous gas dynamic equation.

There are some scientific applications of these types of nonlinear equations. For instance, in ideal gas dynamics, several kinds of waves in nonlinear systems are described including discontinuities in contact, shock fronts and rare factions. It's worth mentioning that many researchers have solved the gas dynamics equations [2, 3]. For the coupled Burgers' equation, it falls into the category of integrable equations, such as nonlinear Schrödinger, Korteweg-De Vries, and Bogoyavlensky-Konopelchenko equations [11, 12, 22, 31].

The structure of this article is as follows: In Section (2), a general structure for the $G N$ of the integral transforms is presented. Then, some theorems for the generalized integral transform of functions are proved in Section (3). As main examples, we prove the constant, polynomial, trigonometric, and exponential functions. In Section (4), we examine some useful properties for the $G N$ of integral transform. In Section (5), our mathematical method is illustrated by using He's polynomial for PDEs with applying the $G N$. In Section (6), based on appropriate $G N$ of integral transforms with He's polynomial method, we present three different examples for nonlinear PDEs: the nonlinear gas dynamic equation, system of coupled nonlinear Burgers' equation and the non-homogeneous gas dynamic equation, the effectiveness of the method is evaluated by deriving the solutions of the
corresponding PDEs.

## 2. A generalization of integral transforms

Here, we present a $G N$ of integral transforms which includes most integral transforms, or even all of them in the class of Laplace transforms (see, e.g., $[8,14,15,17]$ ). In the next definition, we define some functions related to the $G N$, and then formulate the general form of the $G N$. After that, based on this $G N$, the transforms of some functions will be found by proving some theorems.

Definition 1. Assume that the function $F(\Psi(\vartheta) t), t \in[0, \infty)$ is an integrable. Given the positive real functions $h(\vartheta) \neq 0$ and $\sigma(\vartheta)$, the following formula shows the general form of the $G N(G N(\vartheta))$ of $F(\Psi(\vartheta) t)$ :

$$
\begin{align*}
G N[F(t)] & =G N(\vartheta)=h(\vartheta) \int_{0}^{\infty} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t  \tag{1}\\
& =\lim _{\tau \rightarrow \infty} h(\vartheta) \int_{0}^{\tau} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t \tag{2}
\end{align*}
$$

then, when the limit in (2) is exist, we get,

$$
\begin{equation*}
\left|h(\vartheta) \int_{0}^{\tau^{\prime}} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t\right| \leq h(\vartheta) \int_{0}^{\tau^{\prime}}\left|F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t}\right| t \longrightarrow 0, \tag{3}
\end{equation*}
$$

where, $\tau \rightarrow \infty$ for all $\tau^{\prime}>\tau$. Then $\operatorname{GN}(F(\Psi(\vartheta) t) ; \vartheta)$ will be convergence.
Definition 2. Let $F(t)$, has an exponential order $\kappa$, which means, for any $L>0, \exists M>0$, where $\kappa, L$ and $M$ are constants, such that:

$$
\begin{equation*}
|F(t)| \leq M e^{\kappa t}, \quad t>L . \tag{4}
\end{equation*}
$$

## 3. Results of the preliminary study

In this section, we will establish the theorems needed that can be used to demonstrate the $G N$ of integral transforms for solving PDEs.

Theorem 1. Using the $G N$ of integral transforms in the definition 1, we can get the generalized transforms for bellow functions:
(1.A) When $F(t)=1$, then

$$
\begin{align*}
G N[1] & =h(\vartheta) \int_{0}^{\infty} e^{-\sigma(\vartheta) t} t, \\
& =\left.\frac{-h(\vartheta)}{\sigma(\vartheta)} e^{-\sigma(\vartheta) t}\right|_{0} ^{\infty}=\frac{h(\vartheta)}{\sigma(\vartheta)} . \tag{5}
\end{align*}
$$

J.I. Mustafa / Eur. J. Pure Appl. Math, 16 (2) (2023), 1024-1046
(1.B) When $F(t)=t$, then

$$
G N[t]=h(\vartheta) \int_{0}^{\infty} \psi(\vartheta) t e^{-\sigma(\vartheta) t} t
$$

by integrating by parts, we obtain

$$
\begin{equation*}
G N[t]=\frac{h(\vartheta) \psi(\vartheta)}{\sigma^{2}(\vartheta)} . \tag{6}
\end{equation*}
$$

(1.C) When $F(t)=t^{n}$, then

$$
\begin{equation*}
G N\left[t^{n}\right]=\frac{n!h(\vartheta) \psi^{n}(\vartheta)}{\sigma^{n+1}(\vartheta)} . \tag{7}
\end{equation*}
$$

(1.D) When $F(t)=\sin (t)$, then

$$
G N[\sin (t)]=h(\vartheta) \int_{0}^{\infty} \sin (\psi(\vartheta) t) e^{-\sigma(\vartheta) t} t
$$

using integrating by part twice, we obtain:

$$
\begin{equation*}
G N[\sin (t)]=\frac{h(\vartheta) \psi(\vartheta)}{\sigma^{2}(\vartheta)+\psi^{2}(\vartheta)}, \tag{8}
\end{equation*}
$$

(1.E) When $F(t)=e^{t}$, then

$$
\begin{equation*}
G N\left[e^{t}\right]=\frac{h(\vartheta)}{\sigma(\vartheta)-\psi(\vartheta)} . \tag{9}
\end{equation*}
$$

Theorem 2. Suppose $F(t)$ is differentiable, if $F(t)$ and it's derivatives $\left(F^{\prime}(t), F^{\prime \prime}(t), \ldots, F^{(n-1)}(t)\right)$ are of exponential order $\kappa$ and are piecewise continuous on $[0, \infty)$ and the $n^{\text {th }}$ derivative $F^{(n)}(t)$ is a piecewise continuous on $[0, \infty)$, then,
(2.A)

$$
\begin{equation*}
G N\left[F^{\prime}(t)\right]=-\frac{h(\vartheta)}{\Psi(\vartheta)} F(0)+\frac{\sigma(\vartheta)}{\Psi(\vartheta)} G N[F(t)], \tag{10}
\end{equation*}
$$

and,
(2.B)

$$
\begin{equation*}
G N\left[F^{\prime \prime}(t)\right]=-\frac{h(\vartheta)}{\Psi(\vartheta)} F^{\prime}(0)-\frac{h(\vartheta) \sigma(\vartheta)}{\Psi^{2}(\vartheta)} F(0)+\frac{\sigma^{2}(\vartheta)}{\Psi^{2}(\vartheta)} G N[F(t)], \tag{11}
\end{equation*}
$$

then, in general,
(2.C)

$$
\begin{equation*}
G N\left[F^{n}(t)\right]=\frac{\sigma^{n}(\vartheta)}{\Psi^{n}(\vartheta)} G N[F(t)]-\sum_{k=0}^{n-1} \frac{h(\vartheta) \sigma^{n-k-1}(\vartheta)}{\Psi^{n-k}(\vartheta)} F^{(k)}(0) . \tag{12}
\end{equation*}
$$

Proof. (2.A) To find $G N\left[F^{\prime}(t)\right]$, we can integrate as follows:

$$
G N\left[F^{\prime}(t)\right]=h(\vartheta) \int_{0}^{\infty} F^{\prime}(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t .
$$

Using integrating by part, we get,

$$
\begin{align*}
G N\left[F^{\prime}(t)\right] & =h(\vartheta)\left[\left.\frac{1}{\Psi(\vartheta)} e^{-\sigma(\vartheta) t} F(\Psi(\vartheta) t)\right|_{0} ^{\infty}-\int_{0}^{\infty} \frac{-\sigma(\vartheta)}{\Psi(\vartheta)} e^{-\sigma(\vartheta) t} F(\Psi(\vartheta) t) t\right] \\
& =\frac{-h(\vartheta)}{\Psi(\vartheta)} F(0)+\frac{\sigma(\vartheta)}{\Psi(\vartheta)} G N[F(t)] . \tag{13}
\end{align*}
$$

Proof. (2.B) To find $G N\left[F^{\prime \prime}(t)\right]$ : Let $\mathcal{F}(t)=F^{\prime}(t)$, then $\mathcal{F}^{\prime}(t)=F^{\prime \prime}(t)$. Since we know,

$$
\begin{equation*}
G N\left[\mathcal{F}^{\prime}(t)\right]=\frac{-h(\vartheta)}{\Psi(\vartheta)} \mathcal{F}(0)+\frac{\sigma(\vartheta)}{\Psi(\vartheta)} G N[\mathcal{F}(t)], \tag{14}
\end{equation*}
$$

substitute $\mathcal{F}^{\prime}(t)=F^{\prime \prime}(t)$, and $\mathcal{F}(t)=F^{\prime}(t)$ in (14), we have

$$
G N\left[F^{\prime \prime}(t)\right]=\frac{-h(\vartheta)}{\Psi(\vartheta)} F^{\prime}(0)+\frac{\sigma(\vartheta)}{\Psi(\vartheta)} G N\left[F^{\prime}(t)\right] .
$$

Using the relation (2.A), we get,

$$
G N\left[F^{\prime \prime}(t)\right]=\frac{-h(\vartheta)}{\Psi(\vartheta)} F^{\prime}(0)+\frac{\sigma(\vartheta)}{\Psi(\vartheta)}\left[\frac{-h(\vartheta)}{\Psi(\vartheta)}(\vartheta) F(0)+\frac{\sigma(\vartheta)}{\Psi(\vartheta)} G N[F(t)]\right],
$$

then,

$$
\begin{equation*}
G N\left[F^{\prime \prime}(t)\right]=\frac{-h(\vartheta)}{\Psi(\vartheta)} F^{\prime}(0)-\frac{h(\vartheta) \sigma(\vartheta)}{\Psi^{2}(\vartheta)} F(0)+\frac{\sigma^{2}(\vartheta)}{\Psi^{2}(\vartheta)} G N[F(t)] . \tag{15}
\end{equation*}
$$

It is also possible to prove the general form (2.C) in (12) in a similar way.
Theorem 3. Suppose that $h(\vartheta)$ and $\sigma(\vartheta)$ are differentiable and $\sigma^{\prime}(\vartheta) \neq 0$, then,
(3.A)

$$
\begin{equation*}
G N[t F(t)]=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(t)]}{h(\vartheta)}\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta}(F(\Psi(\vartheta) t)) e^{-\sigma(\vartheta) t} t . \tag{16}
\end{equation*}
$$

(3.B)

$$
\begin{align*}
G N\left[t^{2} F(t)\right] & =\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(t)]}{h(\vartheta)}\right)\right)\right)\right) \\
& -\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \bar{\vartheta}(F(\Psi(\vartheta) t)) e^{-\sigma(\vartheta) t} t\right)\right)\right) \\
& +\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} t \bar{\vartheta}(F(\Psi(\vartheta) t)) e^{-\sigma(\vartheta) t} t . \tag{17}
\end{align*}
$$

(3.C) In general,

$$
\begin{align*}
G N\left[t^{n} F(t)\right] & =(-1)^{n} \frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \underbrace{\left(\overline { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{n-1 \text { times }}\left(\bar{\vartheta}\left(\frac{G N[F(t)]}{h(\vartheta)}\right)\right))))) \\
& +\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \sum_{k=0}^{n-1}(-1)^{k} \underbrace{\left(\overline { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{k \text { times }} \\
& \left.\left.\left.\times\left(\int_{0}^{\infty}(t)^{n-k-1}{ }_{\bar{\vartheta}}(F(\Psi(\vartheta) t)) e^{-\sigma(\vartheta) t} t\right)\right)\right)\right) . \tag{18}
\end{align*}
$$

(3.D)

$$
\begin{equation*}
G N\left[t F^{\prime}(t)\right]=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \bar{\vartheta}\left(\frac{G N\left[F^{\prime}(t)\right]}{h(\vartheta)}\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta}\left(F^{\prime}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta)} t . \tag{19}
\end{equation*}
$$

## (3.E)

$$
\begin{equation*}
G N\left[t F^{\prime \prime}(t)\right]=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \bar{\vartheta}\left(\frac{G N\left[F^{\prime}(t)\right]}{h(\vartheta)}\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta}\left(F^{\prime \prime}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta) t} t . \tag{20}
\end{equation*}
$$

(3.F) In general,

$$
\begin{equation*}
G N\left[t F^{(n)}(t)\right]=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \bar{\vartheta}\left(\frac{G N\left[F^{(n)}(t)\right]}{h(\vartheta)}\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta}\left(F^{(n)}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta) t} t . \tag{21}
\end{equation*}
$$

Proof. (3.A)
By using the definition of the $G N$ in equation (1),

$$
\begin{aligned}
& G N[F(t)]=h(\vartheta) \int_{0}^{\infty} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t, \\
& \frac{G N[F(t)]}{h(\vartheta)}=\int_{0}^{\infty} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t,
\end{aligned}
$$

derive both side with respect to $\vartheta$, gives,

$$
\begin{aligned}
\bar{\vartheta}\left(\frac{G N[F(t)]}{h(\vartheta)}\right) & =\int_{0}^{\infty} \bar{\vartheta}\left(F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t}\right) t \\
& =\int_{0}^{\infty}\left(-t F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} \sigma^{\prime}(\vartheta)+\frac{F(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t}\right) t \\
& =-\frac{\sigma^{\prime}(\vartheta)}{h(\vartheta)} h(\vartheta) \int_{0}^{\infty} t F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t+\int_{0}^{\infty} \frac{F(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t} t \\
& =-\frac{\sigma^{\prime}(\vartheta)}{h(\vartheta)} G N[t F(t)]+\int_{0}^{\infty} \frac{F(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t} t
\end{aligned}
$$

then,

$$
G N[t F(t)]=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(t)]}{h(\vartheta)}\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t
$$

Proof. (3.B)
Using the formula in (3.A) and the definition of the $G N$ in equation (1)
$G N[t F(t)]=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(t)]}{h(\vartheta)}\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t$,
$h(\vartheta) \int_{0}^{\infty} F(\Psi(\vartheta) t) t e^{-\sigma(\vartheta) t} t=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(t)]}{h(\vartheta)}\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t$,
derive both side with respect to $\vartheta$, gives,

$$
\begin{aligned}
& \int_{0}^{\infty} F(\Psi(\vartheta) t) t^{2}\left(-\sigma^{\prime}(\vartheta)\right) e^{-\sigma(\vartheta) t} t+\int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) t e^{-\sigma(\vartheta) t} t= \\
& -\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(\Psi(\vartheta) t)]}{h(\vartheta)}\right)\right)\right)+\overline{\bar{\vartheta}}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) t e^{-\sigma(\vartheta) t} t\right)\right)
\end{aligned}
$$

so,

$$
\begin{aligned}
& -\frac{\sigma(\vartheta)}{h(\vartheta)} G N\left[t^{2} F(t)\right]+\int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) t e^{-\sigma(\vartheta) t} t= \\
& -\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(\Psi(\vartheta) t)]}{h(\vartheta)}\right)\right)\right)+\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) t e^{-\sigma(\vartheta) t} t\right)\right),
\end{aligned}
$$

then,

$$
\begin{aligned}
& G N\left[t^{2} F(t)\right]=\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N[F(\Psi(\vartheta) t)]}{h(\vartheta)}\right)\right)\right)\right)- \\
& \frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t\right)\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \bar{\vartheta} F(\Psi(\vartheta) t) t e^{-\sigma(\vartheta) t} t\right)
\end{aligned}
$$

We can prove the general case (3.C) of theorem (3) in a similar way.
Proof. (3.D)
Since,

$$
\begin{aligned}
& G N\left[F^{\prime}(t)\right]=h(\vartheta) \int_{0}^{\infty} F^{\prime}(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t \\
& \frac{G N\left[F^{\prime}(t)\right]}{h(\vartheta)}=\int_{0}^{\infty} F^{\prime}(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t,
\end{aligned}
$$

derive both side with respect to $\vartheta$, gives,

$$
\begin{aligned}
\bar{\vartheta}\left(\frac{G N\left[F^{\prime}(t)\right]}{h(\vartheta)}\right) & =\int_{0}^{\infty} \bar{\vartheta}\left(F^{\prime}(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t}\right) t \\
& =\int_{0}^{\infty}\left(-t F^{\prime}(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} \sigma^{\prime}(\vartheta)+\frac{F^{\prime}(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t}\right) t \\
& =-\frac{\sigma^{\prime}(\vartheta)}{h(\vartheta)} h(\vartheta) \int_{0}^{\infty} t F^{\prime}(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t+\int_{0}^{\infty} \frac{F^{\prime}(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t} t \\
& =-\frac{\sigma^{\prime}(\vartheta)}{h(\vartheta)} G N\left[t F^{\prime}(t)\right]+\int_{0}^{\infty} \frac{F^{\prime}(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t} t
\end{aligned}
$$

then,

$$
\begin{equation*}
G N\left[t F^{\prime}(t)\right]=-\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N\left[F^{\prime}(t)\right]}{h(\vartheta)}\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \frac{F^{\prime}(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t} t \tag{22}
\end{equation*}
$$

We can prove the forms (3.E) and (3.F) of theorem (3) in similar way.
Theorem 4. Given these functions $h(\vartheta), \sigma(\vartheta)$ and $F(t)$ are differentiable $\left(\sigma^{\prime}(\vartheta) \neq 0\right)$, then we can prove

$$
\begin{align*}
G N\left[t^{2} F^{(n)}(t)\right]= & \frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N\left[F^{(n)}\right]}{h(\vartheta)}\right)\right)\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \\
& \times\left(\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \frac{F^{(n)}(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta) t} t\right)\right)\right) \\
& +\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} t \frac{F^{(n)}(\Psi(\vartheta) t)}{\vartheta} e^{-\sigma(\vartheta)} t \tag{23}
\end{align*}
$$

Proof. Recall the general form (3.F) of theorem (3),

$$
\begin{align*}
G N & {\left[t F^{(n)}(t)\right]=h(\vartheta) \int_{0}^{\infty} t F^{(n)}(\Psi(\vartheta t)) e^{-\sigma(\vartheta) t} t } \\
& =-\frac{h}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N\left[F^{(n)}(t)\right]}{h(\vartheta)}\right)\right)+\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \int_{0}^{\infty} \bar{\vartheta}\left(F^{(n)}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta) t} t, \tag{24}
\end{align*}
$$

derive both sides of $(24)$ with respect to $\vartheta$, to obtain,

$$
\begin{align*}
& \left.\int_{0}^{\infty} t^{2} F^{(n)}(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t}\left(-\sigma^{\prime}\right) t+\int_{0}^{\infty} t \bar{\vartheta}^{( } F^{(n)}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta) t} t= \\
& -\bar{\vartheta}\left(\frac{h}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N\left[F^{(n)}(t)\right]}{1}\right)\right)\right)+\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \bar{\vartheta}\left(F^{(n)}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta) t} t\right)\right) \tag{25}
\end{align*}
$$

Thus, simplifying more, we prove theorem (4) as follows:

$$
\begin{align*}
\frac{\sigma^{\prime}(\vartheta)}{h(\vartheta)} G N\left[t^{2} F^{(n)}(t)\right]= & \bar{\vartheta}\left(\frac{h}{\sigma^{\prime}(\vartheta)}\left(\bar{\vartheta}\left(\frac{G N\left[F^{(n)}(t)\right]}{1}\right)\right)\right) \\
& -\bar{\vartheta}\left(\frac{1}{\sigma^{\prime}(\vartheta)}\left(\int_{0}^{\infty} \bar{\vartheta}\left(F^{(n)}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta) t} t\right)\right) \tag{26}
\end{align*}
$$

Theorem 5. Let $h(\vartheta)$ and $\sigma(\vartheta)$ and $F(\Psi(\vartheta) t))$ are differentiable $\left(\sigma^{\prime}(\vartheta) \neq 0\right)$, then,
(5.A)

$$
\begin{align*}
& G N\left[t^{n} F^{\prime}(t)\right]=(-1)^{n} \frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \underbrace{\left[\overline { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{n-1 \text { times }}\left(\bar{\vartheta}\left(\frac{G N\left[F^{\prime}(t)\right]}{h(\vartheta)}\right)\right))))] \\
& +\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \sum_{k=0}^{n-1}(-1)^{k} \underbrace{\left[\overline { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{k \text { times }} \\
& \left.\left.\left.\times\left(\int_{0}^{\infty}(t)^{n-k-1}{ }_{\bar{\vartheta}}\left(F^{\prime}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta) t} t\right)\right)\right)\right] . \tag{27}
\end{align*}
$$

## (5.B)

$$
\begin{align*}
& G N\left[t^{n} F^{\prime \prime}(t)\right]=(-1)^{n} \frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \underbrace{\left[\overline { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{n-1 \text { times }}\left(\bar{\vartheta}\left(\frac{G N\left[F^{\prime \prime}(t)\right]}{h(\vartheta)}\right)\right))))] \\
& +\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \sum_{k=0}^{n-1}(-1)^{k} \underbrace{\left[\overline { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{k \text { times }} \\
& \left.\left.\left.\left.\times\left(\int_{0}^{\infty}(t)^{n-k-1} \bar{\vartheta}\left(F^{\prime \prime}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta)} t\right)\right)\right)\right)\right] . \tag{28}
\end{align*}
$$

(5.C)

$$
\begin{align*}
& G N\left[t^{n} F^{(m)}(t)\right]= \\
& (-1)^{n} \frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \underbrace{\left[\overline { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{n-1 \text { times }}\left(\bar{\vartheta}\left(\frac{G N\left[F^{(m)}(t)\right]}{h(\vartheta)}\right)\right))))] \\
& +\frac{h(\vartheta)}{\sigma^{\prime}(\vartheta)} \sum_{k=0}^{n-1}(-1)^{k} \underbrace{\left[\frac { 1 } { \vartheta } \left(\frac { 1 } { \sigma ^ { \prime } ( \vartheta ) } \left(\overline { \vartheta } \left(\frac{1}{\sigma^{\prime}(\vartheta)} \cdots\right.\right.\right.\right.}_{k \text { times }} \\
& \left.\left.\left.\left.\times\left(\int_{0}^{\infty}(t)^{n-k-1} \bar{\vartheta}\left(F^{(m)}(\Psi(\vartheta) t)\right) e^{-\sigma(\vartheta)} t\right)\right)\right)\right)\right] \tag{29}
\end{align*}
$$

where, in the same way as the theorems (2-4), this theorem is proven.

## 4. Some properties of the generalization of integral transforms

Here, we study some properties for the $G N$ of integral transforms.
Theorem 6. (Linearity property) Let $S(t)$ and $P(t)$ be functions defined for $t \geq 0$, then,

$$
\begin{equation*}
G N\{\eta S(t)+\omega P(t)\}=\eta G N\{S(t)\}+\omega G N\{P(t)\} \tag{30}
\end{equation*}
$$

here, $\eta$ and $\omega$ are scalers.
Proof. Depending on the definition of the $G N$ of integral transforms, we obtain:

$$
\begin{align*}
G N\{\eta S(t)+\omega P(t)\} & =h(\vartheta) \int_{0}^{\infty}[\eta S(\Psi(\vartheta) t)+\omega P(\Psi(\vartheta) t)] e^{-\sigma(\vartheta) t} t \\
& =\eta h(\vartheta) \int_{0}^{\infty} S(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t+\omega h(\vartheta) \int_{0}^{\infty} P(\Psi(\vartheta) t) e^{-\sigma(\vartheta) t} t \\
& =\eta G N\{S(t)\}+\omega G N\{P(t)\} . \tag{31}
\end{align*}
$$

Theorem 7. (Convolution property) If $S(t)$ and $P(t)$ are of exponential order and piecewise continuous on $[0,1)$, then,

$$
\begin{equation*}
G N\{S(t) * P(t)\}=G N_{1}\{S(t)\} G N_{2}\{P(t)\} \tag{32}
\end{equation*}
$$

Proof. Applying the general transform $G N$ on both functions $S(t)$ and $P(t)$, we obtain

$$
G N_{1}\{S(t)\}=h(\vartheta) \int_{0}^{\infty} S(\Psi(\vartheta) \epsilon) e^{-\sigma(\vartheta) \epsilon} \epsilon,
$$

$$
\begin{align*}
G N_{2}\{P(t)\} & =h(\vartheta) \int_{0}^{\infty} P(\Psi(\vartheta) \nu) e^{-\sigma(\vartheta) \nu} \nu \\
G N_{1}\{S(t)\} G N_{2}\{P(t)\} & =\left(h(\vartheta) \int_{0}^{\infty} S(\Psi(\vartheta) \epsilon) e^{-\sigma(\vartheta) \epsilon} \epsilon\right) \times\left(h(\vartheta) \int_{0}^{\infty} P(\Psi(\vartheta) \nu) e^{-\sigma(\vartheta) \nu} \nu\right) \\
& =h^{2}(\vartheta)\left(\int_{0}^{\infty} \int_{0}^{\infty} S(\Psi(\vartheta) \epsilon) P(\Psi(\vartheta) \nu) e^{-\sigma(\vartheta)(\epsilon+\nu)} \epsilon \nu\right) \\
& =h^{2}(\vartheta) \int_{0}^{\infty} S(\Psi(\vartheta) \nu) \nu \int_{0}^{\infty} P(\Psi(\vartheta) \epsilon) e^{-\sigma(\vartheta)(\epsilon+\nu)} \epsilon \tag{33}
\end{align*}
$$

Let,

$$
\begin{equation*}
t=\epsilon+\nu, \quad t=\epsilon \tag{34}
\end{equation*}
$$

substitute (34) into (33), leads to

$$
\begin{aligned}
G N_{1}\{S(t)\} G N_{2}\{P(t)\} & =h^{2}(\vartheta) \int_{0}^{\infty} S(\Psi(\vartheta) \nu) \nu \int_{0}^{\infty} e^{-\sigma(\vartheta) t} P(\Psi(\vartheta)(t-\nu)) t \\
& =h^{2}(\vartheta) \int_{0}^{\infty} e^{-\sigma(\vartheta) t} t \int_{0}^{t} S(\Psi(\vartheta) \nu) P(\Psi(\vartheta)(t-\nu)) \nu \\
& =h(\vartheta) \int_{0}^{\infty} e^{-\sigma(\vartheta) t}\left(h(\vartheta) \int_{0}^{t} S(\Psi(\vartheta) \nu) P(\Psi(\vartheta)(t-\nu)) \nu\right) t
\end{aligned}
$$

So,

$$
\begin{equation*}
G N_{1}\{S(t)\} G N_{2}\{P(t)\}=G N\{S(t) * P(t)\} \tag{35}
\end{equation*}
$$

Theorem 8. (Commutativity property) The convolution between two functions is commutative.

Proof. Let $S(t)$ and $P(t)$, then

$$
\begin{equation*}
S(t) * P(t)=h(\vartheta) \int_{0}^{\infty} e^{-\sigma(\vartheta) \nu} S(\Psi(\vartheta) \nu) P(\Psi(\vartheta)(t-\nu)) \nu \tag{36}
\end{equation*}
$$

Suppose,

$$
\begin{equation*}
t-\nu=\omega, \quad-\nu=\omega \tag{37}
\end{equation*}
$$

substitute the relation in (37) into (36), gives,

$$
\begin{aligned}
S(t) * P(t) & =-h(\vartheta) \int_{t}^{-\infty} e^{-\sigma(\vartheta)(t-\omega)} S(\Psi(\vartheta)(t-\omega)) P(\Psi(\vartheta) \omega) \omega \\
& =h(\vartheta) \int_{0}^{\infty} e^{-\sigma(\vartheta) \omega} P(\Psi(\vartheta) \omega) S(\Psi(\vartheta)(t-\omega)) \omega
\end{aligned}
$$

So,

$$
\begin{equation*}
S(t) * P(t)=P(t) * S(t) \tag{38}
\end{equation*}
$$

## 5. Mathematical Method: The generalization of integral transforms with He's polynomial for the PDEs

As a starting point, we consider nonlinear PDEs in the following equation:

$$
\begin{equation*}
\dot{\mathcal{L}}[g(x, t)]+R[g(x, t)]+\mathcal{G}(x, t)=0, \tag{39}
\end{equation*}
$$

here, $\dot{\mathcal{L}}$ is an invertible operator of first order, $R$ consists of linear as well as nonlinear functions, $g(x, 0)$ is the initial condition (IC) for (39) and $g(x, 0)$ and $\mathcal{G}(x, t)$ are both known functions.
First, the $G N$ to (39) can be applied as:

$$
\begin{equation*}
G N[\dot{\mathcal{L}}[g(x, t)]]+G N[R[g(x, t)]]+G N[\mathcal{G}(x, t)]=0 . \tag{40}
\end{equation*}
$$

Now, the IC of (39) and theorem (2) will be used as follows,

$$
\begin{align*}
& -\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)+\frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]+G N[R[g(x, t)]]+G N[\mathcal{G}(x, t)]=0, \\
& \frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]=\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)-(G N[R[g(x, t)]]+G N[\mathcal{G}(x, t)]), \\
& G N[g(x, t)]=\frac{\psi(\vartheta)}{\sigma(\vartheta)}\left(\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)-(G N[R[g(x, t)]]+G N[\mathcal{G}(x, t)])\right), \\
& G N[g(x, t)]=\frac{h(\vartheta)}{\sigma(\vartheta)} g(x, 0)-\frac{\psi(\vartheta)}{\sigma(\vartheta)}(G N[R[g(x, t)]]+G N[\mathcal{G}(x, t)]) . \tag{41}
\end{align*}
$$

Taking the inverse of the $G N$ of integral transforms ( $G N^{-1}$ ) to (41), we can find $g(x, t)$, this yields,

$$
\begin{equation*}
g(x, t)=g(x, 0)-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N[R[g(x, t)]+\mathcal{G}(x, t)]\right] . \tag{42}
\end{equation*}
$$

So, the solution can be represented by an infinite series:

$$
\begin{equation*}
g(x, t)=\sum_{n=0}^{\infty} g_{n}(x, t), \tag{43}
\end{equation*}
$$

and by using He's polynomial, we will deal with the nonlinear parts

$$
\begin{equation*}
R[g(x, t)]=\sum_{n=0}^{\infty} \mathcal{H}_{n} \tag{44}
\end{equation*}
$$

where, $\mathcal{H}_{n}$ is defined as fallow

$$
\begin{equation*}
\mathcal{H}_{n}\left(g_{0}, \ldots, g_{n}\right)=\frac{1}{n!} \frac{\partial^{n}}{\partial p^{n}}\left[R\left(\sum_{n=0}^{\infty} p^{n} g_{n}(x, t)\right)\right]_{p=0} \tag{45}
\end{equation*}
$$

here, $n=0,1,2, \ldots$, substitute (43) and (44) into (42), gives:

$$
\begin{equation*}
\sum_{n=0}^{\infty} g_{n}(x, t)=g(x, 0)-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\sum_{n=0}^{\infty} \mathcal{H}_{n}^{m}+\sum_{n=0}^{\infty} g_{n}(x, t)+\mathcal{G}(x, t)\right]\right] \tag{46}
\end{equation*}
$$

where, $m$ represents the number of nonlinear terms in (39). Compering both sides of (46), we obtain,

$$
\begin{aligned}
& g_{0}(x, t)=g(x, 0) \\
& g_{1}(x, t)=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{0}^{m}+g_{0}+\mathcal{G}(x, t)\right]\right] \\
& g_{2}(x, t)=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{1}^{m}+g_{1}+\mathcal{G}(x, t)\right]\right]
\end{aligned}
$$

then, the general form will be as,

$$
\begin{equation*}
g_{n+1}(x, t)=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{n}^{m}+g_{n}+\mathcal{G}(x, t)\right]\right] \tag{47}
\end{equation*}
$$

here, $n \geq 0$. This calculation results a series expression and the convergence of this expression leads to an approximate solution.

## 6. Examples: Numerical results for nonlinear PDEs

Here, we apply our mathematical method to three different examples of PDEs.
Example 1. Let us consider the nonlinear equation for gas dynamics,

$$
\begin{align*}
g_{t}(x, t) & =-g(x, t) g_{x}(x, t)+g(x, t)(1-g(x, t))  \tag{48}\\
g(x, 0) & =e^{-x}
\end{align*}
$$

Here, $\mathcal{G}(x, t)=0$, first, we apply the $G N$ integral transforms of (48):

$$
\begin{aligned}
& -\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)+\frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]=G N\left[-g g_{x}+g-g^{2}(x, t)\right] \\
& \frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]=\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)+G N\left[-g g_{x}+g-g^{2}(x, t)\right]
\end{aligned}
$$

multiply both side by $\frac{\psi(\vartheta)}{\sigma(\vartheta)}$, gives

$$
\begin{equation*}
G N[g(x, t)]=\frac{h(\vartheta)}{\sigma(\vartheta)} \mathrm{e}^{-x}+\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g g_{x}+g-g^{2}(x, t)\right] \tag{49}
\end{equation*}
$$

take $G N^{-1}$ to (49), then we obtain:

$$
g(x, t)=G N^{-1}\left[\frac{h(\vartheta)}{\sigma(\vartheta)} \mathrm{e}^{-x}+\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g g_{x}+g-g^{2}(x, t)\right]\right]
$$

$$
\begin{equation*}
g(x, t)=e^{-x}+G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g g_{x}+g-g^{2}(x, t)\right]\right] \tag{50}
\end{equation*}
$$

Now, we deal with the nonlinear parts $g g_{x}$ and $g^{2}$ by using He's polynomial. So, using the general form (47) will give,

$$
\begin{equation*}
g_{n+1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{n}^{1}-g_{n}+\mathcal{H}_{n}^{2}\right]\right], \quad n \geq 0 \tag{51}
\end{equation*}
$$

where, $\mathcal{H}^{1}=g g^{\prime}$ and $\mathcal{H}^{2}=g^{2}$, and $g_{0}=e^{-x}$, using the formula (45), we have

$$
\begin{align*}
& \mathcal{H}_{0}^{1}=g_{0} g_{0}^{\prime}=-e^{-2 x}  \tag{52}\\
& \mathcal{H}_{0}^{2}=g_{0}^{2}=e^{-2 x} \tag{53}
\end{align*}
$$

So,

$$
\begin{aligned}
g_{1}(x, t) & =-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{0}^{1}-g_{0}+\mathcal{H}_{0}^{2}\right]\right] \\
& =-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-e^{-2 x}-e^{-x}+e^{-2 x}\right]\right] \\
& =G N^{-1}\left[\frac{\psi(\vartheta) e^{-x}}{\sigma(\vartheta)} G N[1]\right] \\
& =G N^{-1}\left[\frac{\psi(\vartheta) e^{-x}}{\sigma(\vartheta)} \times \frac{h(\vartheta)}{\sigma(\vartheta)}\right]
\end{aligned}
$$

then,

$$
\begin{equation*}
g_{1}(x, t)=t e^{-x} \tag{54}
\end{equation*}
$$

The next step, we need,

$$
\begin{align*}
& \mathcal{H}_{1}^{1}=g_{0} g_{1}^{\prime}+g_{1} g_{0}^{\prime}=-2 t e^{-2 x}  \tag{55}\\
& \mathcal{H}_{1}^{2}=2 g_{0} g_{1}=2 t e^{-2 x} \tag{56}
\end{align*}
$$

So, the second iteration is:

$$
\begin{aligned}
g_{2}(x, t) & =-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{1}^{1}-g_{1}+\mathcal{H}_{1}^{2}\right]\right] \\
& =-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-2 t e^{-2 x}-t e^{-x}+2 t e^{-2 x}\right]\right] \\
& =G N^{-1}\left[\frac{\psi(\vartheta) e^{-x}}{\sigma(\vartheta)} G N[t]\right] \\
& =G N^{-1}\left[\frac{\psi(\vartheta) e^{-x}}{\sigma(\vartheta)} \times \frac{h(\vartheta) \psi(\vartheta)}{\sigma^{2}(\vartheta)}\right] \\
& =e^{-x} G N^{-1}\left[\frac{h(\vartheta) \psi^{2}(\vartheta)}{\sigma^{3}(\vartheta)}\right]
\end{aligned}
$$



Figure 1: The plot of the solution (59)
then,

$$
\begin{equation*}
g_{2}(x, t)=\frac{1}{2} t^{2} e^{-x} \tag{57}
\end{equation*}
$$

and so on,

$$
\begin{equation*}
g(x, t)=\lim _{n \rightarrow \infty} \sum_{k=0}^{n} g_{k}(x, t)=e^{-x}+t e^{-x}+\frac{1}{2} t^{2} e^{-x}+\ldots . \tag{58}
\end{equation*}
$$

In such a way, the series solution (58) of (48) represents Taylor's expansion of the function $g(x, t)$

$$
\begin{equation*}
g(x, t)=e^{t-x} \tag{59}
\end{equation*}
$$

in the variable $t$ (see Figure (1)).
Example 2. Meditate the system of nonlinear Burgers' equation,

$$
\begin{align*}
& g_{t}(x, t)-g_{x x}(x, t)-2 g(x, t) g_{x}(x, t)+(g(x, t) v(x, t))_{x}=0 \\
& v_{t}(x, t)-v_{x x}(x, t)-2 v(x, t) v_{x}(x, t)+(g(x, t) v(x, t))_{x}=0  \tag{60}\\
& g(x, 0)=\sin (x)=v(x, 0)
\end{align*}
$$

Here, $\mathcal{G}(x, t)=0$. First apply the $G N$ of integral transforms of (60):

$$
\begin{align*}
& -\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)+\frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]=-G N\left[-g_{x x}(x, t)-2 g(x, t) g_{x}(x, t)+(g(x, t) v(x, t))_{x}\right] \\
& -\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)+\frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]=-G N\left[-v_{x x}(x, t)-2 v(x, t) v_{x}(x, t)+(g(x, t) v(x, t))_{x}\right] \tag{61}
\end{align*}
$$

apply $G N^{-1}$ to (61), then we obtain:

$$
\begin{align*}
& g(x, t)=g(x, 0)-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g_{x x}(x, t)-2 g(x, t) g_{x}(x, t)+(g(x, t) v(x, t))_{x}\right]\right], \\
& v(x, t)=v(x, 0)-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-v_{x x}(x, t)-2 v(x, t) v_{x}(x, t)+(g(x, t) v(x, t))_{x}\right]\right] . \tag{62}
\end{align*}
$$

Now, we deal with the nonlinear parts $g g_{x}, v v_{x}$ and $(g v)_{x}$ by using He's polynomial and the general formula (47), as follows:

$$
\begin{align*}
& g_{n+1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g_{n, x x}-2 H_{n}^{1}+\mathcal{H}_{n}^{2}\right]\right], \\
& v_{n+1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-v_{n, x x}-2 H_{n}^{3}+\mathcal{H}_{n}^{2}\right]\right], \tag{63}
\end{align*}
$$

here, $n \geq 0, \mathcal{H}^{1}=g g^{\prime}, \mathcal{H}^{3}=v v^{\prime}$ and $\mathcal{H}^{2}=(g v)_{x}$, and since $g_{0}=v_{0}=\sin (x), H_{n}^{2}=$ $(g v)_{x}=g_{x}^{2}$ or $v_{x}^{2}$, then using the formula (45) yields,

$$
\begin{gathered}
\mathcal{H}_{0}^{1}=g_{0} g_{0}^{\prime}=\sin (x) \cos (x), \quad g_{0}(x, t)=g(x, 0)=\sin (x), \\
\mathcal{H}_{0}^{3}=v_{0} v_{0}^{\prime}=\sin (x) \cos (x), \quad v_{0}(x, t)=v(x, 0)=\sin (x), \\
\mathcal{H}_{0}^{2}=\left(g_{0}^{2}\right)_{x}=2 g_{0} g_{0}^{\prime}=2 \sin (x) \cos (x), \\
g_{1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g_{0, x x}-2 H_{0}^{1}+\mathcal{H}_{0}^{2}\right]\right], \\
v_{0}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-v_{0, x x}-2 H_{0}^{3}+\mathcal{H}_{0}^{2}\right]\right], \\
g_{1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N[\sin (x)-2 \sin (x) \cos (x)+2 \sin (x) \cos (x)]\right], \\
v_{1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N[\sin (x)-2 \sin (x) \cos (x)+2 \sin (x) \cos (x)]\right], \\
g_{1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} \sin (x) \frac{h(\vartheta)}{\sigma(\vartheta)}\right], \\
v_{1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} \sin (x) \frac{h(\vartheta)}{\sigma(\vartheta)}\right], \\
g_{1}=-\sin (x) t, \\
v_{1}=-\sin (x) t .
\end{gathered}
$$



Figure 2: The plot of the solution (65)
So, in the second iteration, we need to find the second He's polynomial,

$$
\begin{align*}
& \mathcal{H}_{1}^{1}=g_{0} g_{1}^{\prime}+g_{0}^{\prime}+g_{1}=2 \sin (x) \cos (x) t, \\
& \mathcal{H}_{1}^{3}=v_{0} v_{1}^{\prime}+v_{0}^{\prime}+v_{1}=2 \sin (x) \cos (x) t,  \tag{64}\\
& \mathcal{H}_{1}^{2}=\left(2 g_{0} g_{1}\right)_{x}=4 \sin (x) \cos (x) t,
\end{align*}
$$

then, substitute (64) into the system (63), yields,

$$
\begin{aligned}
& g_{2}=\frac{1}{2} \sin (x) t^{2} \\
& v_{2}=\frac{1}{2} \sin (x) t^{2}
\end{aligned}
$$

and so on, then, the Taylor's expansion of $g(x, t)$ and $v(x, t)$ give the following solutions (see Figure (2)):

$$
\begin{align*}
& g(x, t)=\lim _{n \rightarrow \infty} \sum_{k=0}^{n} g_{k}=\sin (x) e^{-t},  \tag{65}\\
& v(x, t)=\lim _{n \rightarrow \infty} \sum_{k=0}^{n} v_{k}=\sin (x) e^{-t} .
\end{align*}
$$

Example 3. The non-homogeneous gas dynamic equation is given below,

$$
\begin{align*}
g_{t}(x, t) & =-g(x, t) g_{x}(x, t)+g(x, t)(1-g(x, t))-\mathrm{e}^{t-x},  \tag{66}\\
g(x, 0) & =1-\mathrm{e}^{-x} .
\end{align*}
$$

First take general integral transform of (66) as:

$$
-\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)+\frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]=G N\left[-g g_{x}+g-g^{2}(x, t)\right]-G N\left[\mathrm{e}^{t-x}\right],
$$

$$
\frac{\sigma(\vartheta)}{\psi(\vartheta)} G N[g(x, t)]=\frac{h(\vartheta)}{\psi(\vartheta)} g(x, 0)-\mathrm{e}^{-x} \frac{h(\vartheta)}{\sigma(\vartheta)-\psi(\vartheta)}+G N\left[-g g_{x}+g-g^{2}(x, t)\right]
$$

then, multiply both side by $\frac{\psi(\vartheta)}{\sigma(\vartheta)}$, gives,

$$
\begin{equation*}
G N[g(x, t)]=\frac{h(\vartheta)}{\sigma(\vartheta)}\left(1-\mathrm{e}^{-x}\right)-\mathrm{e}^{-x} \frac{\psi(\vartheta)}{\sigma(\vartheta)} \frac{h(\vartheta)}{\sigma(\vartheta)-\psi(\vartheta)}+\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g g_{x}+g-g^{2}(x, t)\right] \tag{67}
\end{equation*}
$$

take $G N^{-1}$ to (67), we obtain:

$$
\begin{align*}
& g(x, t)=G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)}\left(1-\mathrm{e}^{-x}\right)\right.-\mathrm{e}^{-x} \frac{\psi(\vartheta)}{\sigma(\vartheta)} \frac{h(\vartheta)}{\sigma(\vartheta)-\psi(\vartheta)} \\
&\left.\left.+\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g g_{x}+g-g^{2}(x, t)\right]\right]\right] \\
& g(x, t)=1-\mathrm{e}^{-x}-\mathrm{e}^{-x}\left(\mathrm{e}^{t}-1\right)+G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[-g g_{x}+g-g^{2}(x, t)\right]\right] . \tag{68}
\end{align*}
$$

After that, we will deal with the nonlinear parts $g g_{x}$ and $g^{2}$ by using He's polynomial. So, using the general form (47) will be as,

$$
\begin{equation*}
g_{n+1}=-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{n}^{1}-g_{n}+\mathcal{H}_{n}^{2}\right]\right], n \geq 0 \tag{69}
\end{equation*}
$$

where, $\mathcal{H}^{1}=g g^{\prime}$ and $\mathcal{H}^{2}=g^{2}$, and $g_{0}(x, t)=1-\mathrm{e}^{t-x}$, using the formula (45), we have

$$
\begin{align*}
& \mathcal{H}_{0}^{1}=g_{0} g_{0}^{\prime}=\mathrm{e}^{t-x}-\mathrm{e}^{2(t-x)}  \tag{70}\\
& \mathcal{H}_{0}^{2}=g_{0}^{2}=1-2 \mathrm{e}^{t-x}+\mathrm{e}^{2(t-x)} \tag{71}
\end{align*}
$$

so,

$$
\begin{aligned}
g_{1}(x, t) & =-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{0}^{1}-g_{0}+\mathcal{H}_{0}^{2}\right]\right] \\
& =-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathrm{e}^{t-x}-\mathrm{e}^{2(t-x)}-1+\mathrm{e}^{t-x}+1-2 \mathrm{e}^{t-x}+\mathrm{e}^{2(t-x)}\right]\right] \\
& =G N^{-1}\left[\frac{\psi(\vartheta) e^{-x}}{\sigma(\vartheta)} G N[1]\right] \\
& =0
\end{aligned}
$$

then,

$$
\begin{equation*}
g_{1}(x, t)=0 \tag{72}
\end{equation*}
$$

The next step, we need

$$
\begin{equation*}
\mathcal{H}_{1}^{1}=g_{0} g_{1}^{\prime}+g_{1} g_{0}^{\prime}=0 \tag{73}
\end{equation*}
$$



Figure 3: The plot of the exact solution (76)

$$
\begin{equation*}
\mathcal{H}_{1}^{2}=2 g_{0} g_{1}=0 \tag{74}
\end{equation*}
$$

So,

$$
\begin{aligned}
g_{2}(x, t) & =-G N^{-1}\left[\frac{\psi(\vartheta)}{\sigma(\vartheta)} G N\left[\mathcal{H}_{1}^{1}-g_{1}+\mathcal{H}_{1}^{2}\right]\right] \\
& =0
\end{aligned}
$$

and so on. Thus, the series solution $g(x, t)$

$$
\begin{align*}
g(x, t) & =\lim _{n \rightarrow \infty} \sum_{k=0}^{\infty} g_{k}(x, t) \\
& =1-\mathrm{e}^{t-x}+0+\ldots \tag{75}
\end{align*}
$$

gives the exact solution of (66) (see Figure (3)):

$$
\begin{equation*}
g(x, t)=1-e^{t-x} \tag{76}
\end{equation*}
$$

## 7. Conclusion

We briefly summarized the output of the current paper. First of all, the $G N$ of integral transforms has been developed by formulating a new form of the generalized integral transform. The development started with introducing some definitions about the functions which are related to the $G N$. Then, formulating the theorems of the $G N$, in which we proved that the $G N$ of integral transforms of some functions and the derivatives of unknown functions, which were used in the equations, has been fulfilled. These transforms have been used as an essential tool in determining the solutions to equations. Additionally,
the development of the $G N$ of integral transform involved studying some useful properties. In a second study, a mathematical method has been exhibited by using our newly developed $G N$ together with He's polynomial method to solve nonlinear PDEs where the He's polynomial method evaluates nonlinear terms. For this combination of our $G N$ and He's polynomial method, a convergent series has been obtained. Consequently, a variety of equations have been successfully solved using this combination, including PDEs in three types of equations. The nonlinear gas dynamic equation and the system of coupled nonlinear Burgers' equation have been solved in the first and second examples, respectively, which determined approximate solution (see Figure (1) and (2)), whereas in the third example, the non-homogeneous gas dynamic equation has been solved to obtain an exact solution (see Figure (3)). Finally, the advantages of our method are its efficiency and accuracy as it led to more accurate results and more efficient calculations, as well as the fact that it can be used to solve any order of nonlinear equations. This makes it an invaluable tool for finding the solutions of a various problems in mathematical physics.

## Acknowledgements

The author is very grateful to the "College of Education for Pure Sciences at the University of Mosul, Iraq" for their support of my research.

## References

[1] Shams A Ahmed, Ahmad Qazza, and Rania Saadeh. Exact solutions of nonlinear partial differential equations via the new double integral transform combined with iterative method. Axioms, 11(6):247, 2022.
[2] Hossein Aminikhah and Ali Jamalian. Numerical approximation for nonlinear gas dynamic equation. International Journal of Partial Differential Equations, 2013, 2013.
[3] Mohannad Hamid Eljaily Babiker et al. Solution of Partial Differential Equations with Nonlocal Conditions by Combine Homotopy Perturbation Method and Laplace Transform. PhD thesis, Sudan University of Science and Technology, 2016.
[4] Benedict Barnes, C Sebil, and A Quaye. A generalization of integral transform. 2018.
[5] Rachid Belgacem, Ahmed Bokhari, Mohamed Kadi, and Djelloul Ziane. Solution of non-linear partial differential equations by shehu transform and its applications. Malaya Journal of Matematik, 8(4):1974-1979, 2020.
[6] Changbum Chun. Application of homotopy perturbation method with chebyshev polynomials to nonlinear problems. Zeitschrift für Naturforschung A, 65(1-2):65-70, 2010.
[7] Ravi Shankar Dubey, Pranay Goswami, Vinod Gill, et al. A new analytical method to solve klein-gordon equations by using homotopy perturbation mohand transform method. Malaya Journal of Matematik, 10(1):1-19, 2022.
[8] AI El-Mesady, YS Hamed, and AM Alsharif. Jafari transformation for solving a system of ordinary differential equations with medical application. fractal fract. 2021, 5, 130, 2021.
[9] Asghar Ghorbani. Beyond adomian polynomials: he polynomials. Chaos, Solitons 83 Fractals, 39(3):1486-1492, 2009.
[10] Asghar Ghorbani and Jafar Saberi-Nadjafi. He's homotopy perturbation method for calculating adomian polynomials. International Journal of Nonlinear Sciences and Numerical Simulation, 8(2):229-232, 2007.
[11] Georgi G Grahovski, Amal J Mohammed, and Hadi Susanto. Nonlocal reductions of the ablowitz-ladik equation. Theoretical and Mathematical Physics, 197(1):14121429, 2018.
[12] Georgi G Grahovski, Junaid I Mustafa, and Hadi Susanto. Nonlocal reductions of the multicomponent nonlinear schrödinger equation on symmetric spaces. Theoretical and Mathematical Physics, 197(1):1430-1450, 2018.
[13] Murat Gubes. A new calculation technique for the laplace and sumudu transforms by means of the variational iteration method. Mathematical Sciences, 13:21-25, 2019.
[14] Hossein Jafari. A new general integral transform for solving integral equations. Journal of Advanced Research, 32:133-138, 2021.
[15] C Jesuraj and A Rajkumar. A new modified sumudu transform called raj transform to solve differential equations and problems in engineering and science. International Journal on Emerging Technologies, 11(2):958-964, 2020.
[16] Artion Kashuri, Akli Fundo, and Matilda Kreku. Mixture of a new integral transform and homotopy perturbation method for solving nonlinear partial differential equations. 2013.
[17] Bachir Nour Kharrat. A new integral transform: Kharrat-toma transform and its properties. World Applied Sciences Journal, 38(5):436-443, 2020.
[18] Adem Kıliçman and Rathinavel Silambarasan. Computing new solutions of algebrogeometric equation using the discrete inverse sumudu transform. Advances in Difference Equations, 2018(1):1-17, 2018.
[19] Kevser Köklü. Resolvent, natural, and sumudu transformations: solution of logarithmic kernel integral equations with natural transform. Mathematical Problems in Engineering, 2020, 2020.
[20] MAM Mahgoub and Abdelbagy A Alshikh. An application of new transform "mahgoub transform" to partial differential equations. Mathematical theory and Modeling, $7(1): 7-9,2017$.
[21] Amal Jasim Mohammed, Sohaib Talal Al-Ramadhani, and Rabeea Mohammed Hani Darghoth. The possible solutions for the two kdv-type equations using a semianalytical kamal-iteration method. European Journal of Pure and Applied Mathematics, 15(4):1917-1936, 2022.
[22] Amal Jasim Mohammed and Ahmed Farooq Qasim. A new procedure with iteration methods to solve a nonlinear two dimensional bogoyavlensky-konopelchenko equation. Journal of Interdisciplinary Mathematics, 25(2):537-552, 2022.
[23] Oludapo Omotola Olubanwo, Olutunde Samuel Odetunde, and Adetoro Temitope Talabi. Aboodh homotopy perturbation method of solving burgers equation. Asian Journal of Applied Sciences, 7(2), 2019.
[24] Dinkar Patil. Aboodh and mahgoub transform in boundary value problems of system of ordinary differential equations. DP Patil, Aboodh and Mahgoub Transform in Boundary Value Problems of System of Ordinary Differential Equations, International Journal of Advanced Research in Science, Communication and Technology (IJARSCT), pages 67-75, 2022.
[25] Patarawadee Prasertsang, Supaknaree Sattaso, Kamsing Nonlaopon, and Hwajoon Kim. Analytical study for certain ordinary differential equations with variable coefficients via g $\alpha$-transform. European Journal of Pure and Applied Mathematics, 14(4):1184-1199, 2021.
[26] LS Sawant. Applications of laplace transform in engineering fields. International Research Journal of Engineering and Technology, 5(5):3100-3105, 2018.
[27] Dinkar Sharma, Prince Singh, and Shubha Chauhan. Homotopy perturbation transform method with he's polynomial for solution of coupled nonlinear partial differential equations. Nonlinear engineering, 5(1):17-23, 2016.
[28] Pilasluck Sornkaew and Kanyarat Phollamat. Solution of partial differential equations by using mohand transforms. In Journal of Physics: Conference Series, volume 1850. IOP Publishing, 2021.
[29] Betty Subartini, Ira Sumiati, Riaman Sukono, and Ibrahim Mohammed Sulaiman. Combined adomian decomposition method with integral transform. 2021.
[30] Janki Vashi and MG Timol. Laplace and sumudu transforms and their application. Int. J. Innov. Sci., Eng. Technol, 3(8):538-542, 2016.
[31] Yuan Wei, Li Yin, and Xin Long. The coupling integrable couplings of the generalized coupled burgers equation hierarchy and its hamiltonian structure. Advances in Difference Equations, 2019(1):1-17, 2019.
[32] Djelloul Ziane, Rachid Belgacem, and Ahmed Bokhari. A new modified adomian decomposition method for nonlinear partial differential equations. Open J. Math. Anal, 3:81-90, 2019.

