EUROPEAN JOURNAL OF PURE AND APPLIED MATHEMATICS

Vol. 17, No. 4, 2024, 3356-3369 ISSN 1307-5543 – ejpam.com Published by New York Business Global

On b-Coloring Analysis of Graphs: An Application to Spatial-Temporal Graph Neural Networks for Multi-Step Time Series Forecasting of Soil Moisture and pH in Companion Farming

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Abstract. Let G be a pair of two sets (V, E) with vertex set V and edge set E. A proper coloring of a graph G is a vertex coloring of it such that no two adjacent vertices in G have the same color. By b−Coloring, we define a coloring of the vertex of G such that each color class has at least one vertex that adjacent with all other color classes. The $b - chromatic$ number of graph G, denoted by $\varphi(G)$, is the largest integer k such that graph G has b–Coloring with k colors. In this paper, we will explore some new lemmas or theorems regarding to $\varphi(G)$. Furthermore, to see the robust application of b−Coloring of graph, at the end of this paper we will illustrate the implementation of b−Coloring on spatial temporal graph neural networks (STGNN) multi-step time series forecasting on soil moisture and pH of companion farming.

2020 Mathematics Subject Classifications: 05C78

Key Words and Phrases: b–Coloring, b-chromatic number, companion farming, multi-step time series forecasting

1. Introduction

A classic and well-known graph theory problem is graph coloring. Graph coloring is one of the important branches in graph theory that has been the focus of intensive research in recent years. A graph coloring is considered to be an assignment of colours, labels or weights to the elements of the graphs. For several decades, graph coloring problems have become an extremely useful models for many theoretical and practical problems

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DOI: https://doi.org/10.29020/nybg.ejpam.v17i4.5409

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A. I. Kristiana et al. / Eur. J. Pure Appl. Math, 17 (4) (2024), 3356-3369 3357

[11]. Some types of graph coloring are vertex coloring, total coloring, edge coloring, map coloring, interval coloring, clique coloring, and bipartite graph coloring. Vertex coloring refers to the process of assigning colors to vertices in G so that no two adjacent vertices have the same color. The following are a formal definition of k− coloring of graph.

1.1. Basic Definitions

Definition 1. [6] The minimum number of colors required to properly color a graph G is its chromatic number G, denoted by $\chi(G)$.

Based on these concepts, Irving and Manlove [7] introduced a new concept namely b−Coloring. Kouider and Maheo [8] provided some upper and lower bound of the bchromatic number on b−Coloring of graph. Here is the definition of b−Coloring mentioned in [5, 7, 8].

Definition 2. [7] A b–Coloring of a graph G is a proper vertex coloring in a way that each color class has a at least one vertex that is adjacent to every other color class.

Definition 3. [7] The b−chromatic number of graph G is the highest integer k such that G has a b–Coloring, denoted by $\varphi(G)$.

Lemma 1. [8] For any graph G , $\chi(G) \leq \varphi(G) \leq \Delta(G) + 1$, where $\Delta(G)$ is the highest degree of vertices in G.

Definition 4. [5] Let G and H be two connected graphs. Let o be a vertex of H. The comb product between G and H, denoted by $G \triangleright_{o} H$, is a graph obtained by taking one copy of G and $|V(G)|$ copies of H and grafting the i – th copy of H at the vertex o to the i – th vertex of G.

Vivin and Venkatachalam [12] determined b−Coloring of sun let graph dan wheel graph families, Chandel et al., determined b−Coloring of ladder graph [4], Ansari et al., determined b-coloring of helm graph and prism graph families [2] [3], Akalyadevi and Ramaswamy determined b−Coloring of net graph families [1], and Nagarathinam dan Parvathi determined b−Coloring of line, middle and total graph of tadpole graph, and operator graph of tadpole and wheel graph [9] [10]. Determining the b−Coloring is considered to be NP problem, thus finding the exact value of b−chromatic number is still open for any or specific graphs. Thus, in this study aims to analyze the new results obtained b-chromatic number of $P_n \rhd_{v_1} P_m$ graph for $n, m \geq 8$ and $L_n \rhd_{v_1} P_m$ graph for $n, m \geq 5$.

Furthermore, to see the robust application of b−Coloring of graph, at the end of this paper we will illustrate the implementation of b−Coloring on Spatial Temporal Graph Neural Networks (STGNN) multi-step time series forecasting on soil moisture and pH of companion farming. Companion farming is a system where two or more crops are grown simultaneously on the same farm. Plants are planted alternately in straight rows to create a regular cropping pattern. The use of companion farming aims to minimize crop pests. The b−Coloring analysis on companion farming is used to determine the number of plant species, so that in the same land can be planted various types of plants. There are factors that affect the growth and yield of companion plants, namely soil moisture and pH . Both of these factors can have an impact on productivity and plant health in companion farming.

To predict the soil moisture and pH is very important, since predicting soil moisture and pH is crucial for successful agricultural management and environmental monitoring. Both soil moisture and pH levels play significant roles in determining the health and productivity of plants. The best tool for predicting them is using machine learning, Spatial-Temporal Graph Neural Network (STGNN). A Spatial-Temporal Graph Neural Network (STGNN) is a type of neural network architecture designed to model and analyze data that has both spatial and temporal dependencies, particularly in the context of graphs. It combines concepts from Graph Neural Networks (GNNs) and Temporal models to handle data with both spatial and temporal dimensions. Thus, in this study, we will implement STGNN multi-step time series forecasting for soil moisture and pH .

2. The Methods

The research methods used in this research are pattern recognition method, axiomatic deductive method, and application research method. In this study, it explains related to the application scheme of the Spatial-Temporal Graph Neural Network on the problem of forecasting soil moisture and pH in companion plants with a multi-step time series forecasting. The numerical simulation used to run the programming uses Google Collaborator. Furthermore, STGNN programming will be developed, training the model using 60% input data obtained from the vertex embedding process, testing and finally forecasting soil moisture and pH. Soil moisture and pH are two important factors and affect plant growth conditions and the balance of the soil ecosystem. We use the following algorithm for studying companion planting distribution by using STGNN combined by b−Coloring.

Single Layer STGNN Algorithm

Step 0. Considering a graph $G(V, E)$ of order n with n vertices and m features, a and feature matrix $H_{n\times m}$ from certain companion plantations, and provide a tolerance ϵ .

Step 1. Construct the matrix adjacency A of graph G arising from spatial of companion plantations and set a matrix $B = A + I$, where I is an identity matrix. Step 2. Set weights W to start, bias β , learning rate α . (For ease of understanding, set $W_{m\times 1} = [w_1 \ w_2 \ \dots \ w_m]$, where $0 < w_j < 1$, bias $\beta = 0$ and $0 < \alpha < 1$) $Step \ 3.$ Set a message function $\mathbf{m_u}^l = MSG^l(h_u^{l-1})$ for the linear layer $\mathbf{m_u}^l =$ $W^l(h_u^{l-1})$ to multiply the weight matrix with vertex features. Step 4. Combine the signals from the neighbors of vertex v by setting function

 $h^l_v = AGG^l\{m^{l-1}_u, u\in N(v)\}$, and by utilizing the sum (\cdot) function $h^l_v = SUM^l\{m^{l-1}_u, u\in N\}$ $N(v)$ } in connection with matrix B .

Step 5. Construct the error, by setting $error^l = \frac{||h_{v_i} - h_{v_j}||_2}{|E|}$ $\frac{n_{v_{j}\parallel 2}}{|E|}$, where v_i,v_j are vertices that are next to one other.

Step 6. Check if error $\leq \epsilon$ or not. If yes end the process, if not proceed to refresh the learning weight matrix W in step 7.

 $Step \, \, 7.$ Set $W^{l+1} \, = \, W^{l}_j - \alpha \times z_j \times e^{l}$ for updating the learning weight matrix where the total of each column in the $H_{v_i}^l$ is denoted by z_j and then split by the total number of nodes.

Step 8. If the data is a time series, save the results of the embedding in a vector and repeat the process for the subsequent time data observation. Step 9. After loading the vector data, perform multi-step time series forecasting, testing, and training using the time series machine learning.

Step 10. Is RMSE $\leq \epsilon$? If YES then STOP. If No then improve W, do Step 2-9.

3. Main Result

3.1. b−Coloring

In this paper, we will analyze the new result of the b-chromatic number of $P_n \triangleright_{v_1} P_m$ graph for $n, m \geq 8$ and $L_n \triangleright_{v_1} P_m$ graph for $n, m \geq 5$.

Theorem 1. Let $P_n \triangleright_{v_1} P_m$ be a comb product of graphs for $n \geq 6$, $m \geq 2$. We have $\varphi(P_n \triangleright_{v_1} P_m) = 4.$

Proof. The graph $P_n \rhd_{v_1} P_m$ is a connected graph with vertex set $V(P_n \rhd_{v_1} P_m)$ ${x_{i,j}}; 1 \leq i \leq n, 1 \leq j \leq m$ and edge set $E(P_n \triangleright_{v_1} P_m) = {x_{i,1}x_{i+1,1}}; 1 \leq i \leq n-1$ ∪ $\{x_{i,j}x_{i,j+1}; 1 \leq i \leq n, 1 \leq j \leq m-1\}$. Thus $|V(P_n \rhd_{v_1} P_m)| = nm$ and $|E(P_n \rhd_{v_1} P_m)| =$ $nm-1$. The chromatic number $\gamma(P_n \triangleright_{v_1} P_m) = 2$ and maximum degree $\Delta(P_n \triangleright_{v_1} P_m) = 3$.

To obtain the b-chromatic number $\varphi(P_n \rhd_{v_1} P_m)$ for $n \geq 6, m \geq 2$, we will analyze the upper bound of $P_n \rhd_{v_1} P_m$. Based on Definition 2 and Lemma 1, we have $\chi(P_n \rhd_{v_1}$ P_m) $\leq \varphi(P_n \triangleright_{v_1} P_m) \leq \Delta(P_n \triangleright_{v_1} P_m) + 1 = 4 \longleftrightarrow \varphi(P_n \triangleright_{v_1} P_m) \leq 4.$ Furthermore, we need to find the exact value of $\varphi(P_n \triangleright_{v_1} P_m)$ by defining the coloring function as follows $f: V(P_n \triangleright_{v_1} P_m) \to \{1, 2, 3, ..., k\}$ as follows

$$
f(x_{i,j}) = \begin{cases} 1, & \text{if } i \equiv 2 \mod 4, j \equiv 1 \mod 2 \\ & \text{if } i \equiv 0 \mod 4, j \equiv 0 \mod 2 \\ 2, & \text{if } i \equiv 1 \mod 4, j \equiv 1 \mod 2 \\ & \text{if } i \equiv 3 \mod 4, j \equiv 0 \mod 2 \\ 3, & \text{if } i \equiv 0 \mod 4, j \equiv 1 \mod 2 \\ & \text{if } i \equiv 2 \mod 4, j \equiv 0 \mod 2 \\ 4, & \text{if } i \equiv 3 \mod 4, j \equiv 1 \mod 2 \\ & \text{if } i \equiv 1 \mod 4, j \equiv 0 \mod 2 \end{cases}
$$

Based on the function above, we have $f: V(P_n \triangleright_{v_1} P_m) \to \{1, 2, 3, 4\}$. Thus, we have $k = 4$. It implies that $\varphi(P_n \triangleright_{v_1} P_m) = 4$. The last, we need to show that each color class has at least one vertex that adjacent with all other color classes. According to the coloring function, the b−chromatic number of graph $P_n \triangleright_{v_1} P_m$ is 4, thus we have four color classes, namely $C_1 = \{x_{i,j} | i \equiv 2 \mod 4, j \equiv 1 \mod 2; i \equiv 0 \mod 4, j \equiv 0 \mod 2\}, C_2 = \{x_{i,j} | i \equiv 0 \mod 4, j \equiv 0 \mod 4, j \equiv 0 \mod 4\}$ $1 \mod 4, j \equiv 1 \mod 2; i \equiv 3 \mod 4, j \equiv 0 \mod 2, C_3 = \{x_{i,j} | i \equiv 0 \mod 4, j \equiv 1 \mod 2; i \equiv 1 \mod 4, j \$ $2 \mod 4, j \equiv 0 \mod 2$, $C_4 = \{x_{i,j} | i \equiv 1 \mod 4, j \equiv 0 \mod 2; i \equiv 3 \mod 4, j \equiv 1 \mod 2\}.$ Based on the four color classes, we can show that each color class has at least one vertex that is adjacent to all other color classes. We can show it by depicting the methane-like structure, see Figure 1. Thus, it proves that $\varphi(P_n \triangleright_{v_1} P_m) = 4$ for $n \geq 6, m \geq 2$.

To have more detail illustration of b–Coloring of $P_n \triangleright_{v_1} P_m$, we depict the picture, see Figure 2.

Theorem 2. Let $L_n \rhd_{v_1} P_m$ be a comb product of graphs for $n \geq 5$, $m \geq 2$. We have $\varphi(P_n \triangleright_{v_1} P_m) = 5.$

Proof. The graph $L_n \rhd_{v_1} P_m$ is a connected graph with vertex set $V(L_n \rhd_{v_1} P_m)$ ${x_{i,j}}; 1 \leq i \leq n, 1 \leq j \leq m$ $\cup \{y_{i,j}; 1 \leq i \leq n, 1 \leq j \leq m\}$ and edge set $E(L_n \triangleright_{v_1} P_m)$ ${x_{i,1}x_{i+1,1}}; 1 \leq i \leq n-1$ }∪ ${x_{i,j}x_{i,j+1}}; 1 \leq i \leq n, 1 \leq j \leq m-1$ }∪ ${y_{i,1}y_{i+1,1}}; 1 \leq i \leq n-1$ }∪ $\{y_{i,j}y_{i,j+1}; 1 \leq i \leq n, 1 \leq j \leq m-1\} \cup \{x_{i,1}y_{i,1}; 1 \leq i \leq n\}$. Thus $|V(L_n \triangleright_{v_1} P_m)| = 2nm$ and $|E(L_n \triangleright_{v_1} P_m)| = 2nm+n-2$. The chromatic number $\gamma(L_n \triangleright_{v_1} P_m) = 2$ and maximum degree $\Delta(L_n \triangleright_{v_1} P_m) = 4.$

To obtain the b-chromatic number $\varphi(L_n \rhd_{v_1} P_m)$ for $n \geq 7, m \geq 3$, we will analyze the upper bound of $L_n \rhd_{v_1} P_m$. Based on Definition 2 and Lemma 1, we have $\chi(L_n \rhd_{v_1}$

 P_m) $\leq \varphi(L_n \triangleright_{v_2} P_m) \leq \Delta(L_n \triangleright_{v_2} P_m) + 1 = 5 \longleftrightarrow \varphi(L_n \triangleright_{v_1} P_m) \leq 5$. Furthermore, we need to find the exact value of $\varphi(L_n \triangleright_{v_1} P_m)$ by defining the coloring function as follows $f: V(L_n \rhd_{v_2} P_m) \to \{1, 2, 3, \ldots, k\}$ as follows

Based on the function above, we have $f: V(L_n \triangleright_{v_1} P_m) \to \{1, 2, 3, 4, 5\}$. Thus, we have $k = 5$. It implies that $\varphi(L_n \triangleright_{v_1} P_m) = 5$. The last, we need to show that each color class has at least one vertex that adjacent with all other color classes. According to the labeling, the b–chromatic number of graph $L_n \rhd_{v_1} P_m$ is five, thus we have $C_1 = \{x_{i,j} | i \equiv 1 \mod 5, j \equiv 1 \mod 5 \}$ $1 \mod 2; i \equiv 3 \mod 5, j \equiv 0 \mod 2, C_2 = \{x_{i,j} | i \equiv 2 \mod 5, j \equiv 1 \mod 2; i \equiv 0 \mod 5, j \equiv 1 \mod 5, j \$ 0 mod 2}, $C_3 = \{x_{i,j} | i \equiv 3 \mod 5, j \equiv 1 \mod 2; i \equiv 4 \mod 5, j \equiv 0 \mod 2\}, C_4 = \{x_{i,j} | i \equiv 3 \mod 5, j \equiv 4 \mod 5, j \equiv 0 \mod 2\}$ $4 \mod 5, j \equiv 1 \mod 2; i \equiv 1 \mod 5, j \equiv 0 \mod 2, C_5 = \{x_{i,j} | i \equiv 0 \mod 5, j \equiv 1 \mod 2; i \equiv 1 \mod 5, j \$ $2 \mod 5, j \equiv 0 \mod 2$ and $C_1 = \{y_{i,j} | i \equiv 4 \mod 5, j \equiv 1 \mod 2; i \equiv 2 \mod 5, j \equiv 0 \mod 2\},\$ $C_2 = \{y_{i,j} | i \equiv 0 \mod 5, j \equiv 1 \mod 2; i \equiv 3 \mod 5, j \equiv 0 \mod 2\}, C_3 = \{y_{i,j} | i \equiv 1 \mod 5, j \equiv 1 \mod 5, j \equiv 1 \mod 5\}$ $1 \mod 2; i \equiv 4 \mod 5, j \equiv 0 \mod 2, C_4 = \{y_{i,j} | i \equiv 2 \mod 5, j \equiv 1 \mod 2; i \equiv 0 \mod 5, j \equiv 1 \mod 5, j \$ 0 mod 2, $C_5 = \{y_{i,j} | i \equiv 3 \mod 5, j \equiv 1 \mod 2; i \equiv 1 \mod 5, j \equiv 0 \mod 2\}$. Based on the five color classes, we can show that each color class has at least one vertex that is adjacent to all other color classes. We can show it by depicting the methane-like structure, see Figure 3. Thus, it proves that $\varphi(P_n \triangleright_{v_1} P_m) = 5$ for $n \geq 5, m \geq 2$.

To have more detail illustration of b–Coloring of $L_n \rhd_{v_1} P_m$, we depict the picture, see Figure 4.

3.2. The Application of b−Coloring

The next research result is the implementation of b−Coloring on precision agriculture companion farming. In this research, time series forecasting will be performed on precision agriculture datasets, namely soil moisture and pH . The datasets are obtained from simulating the placement of soil moisture and pH sensors. The placement of these sensors takes into account the planting topology derived from Theorem 1. The number of plantations is respected to the obtained b-chromatic number $\varphi(G)$.

Based on the $P_n \triangleright_{v_1} P_m$ graph we can make into a planting layout adapted to the shape of the land. In each vertex, the coloring obtained represents a type of plant. Since $\varphi(P_n \triangleright_{v_1} P_m) = 4$, there are four types of plants studied. In this study, the color 1 represents cucumbers, the color 2 represents carrots, the color 3 represents tomatoes, and the color 4 represents eggplants. Furthermore, the sensor is placed at the vertex of dominance on the planting layout created. The companion farming layout based on b−Coloring theorem can be seen in Figure 5 and Figure 6.

3.3. Numerical Analysis

Hereafter, we discuss the research results and provide an overview to perform time series forecasting in companion farming. First, we show analytically how to embed node features and how b−Coloring works on graphs. We use soil moisture and pH data to derive the STGNN model.

Observation 1. Given that there is a n-order graph G . Assume that the set of vertex $V(G) = \{v_1, v_2, ..., v_{n-1}, v_n\}$ and and edge of vertex $E(G) = \{v_i v_j | v_i, v_j \in V(G)\}$, respec-

Table 1: The prediction results of STGNN model for dataset-1

T	Matric	HА	ARIMA	SVR	GCN	GRU	STGNN
	RMSE	9.4546	10.6872	9.7862	11.1382	7.5492	6.2187
6 days	MAE	8.7113	8.9815	9.4121	10.6702	7.6615	6.4357
	Accuracy	5.5673	6.7890	9.3423	8.2732	8.4351	10.1431
	R^2	4.28512	4.3482	7.9563	8.0321	8.4321	9.1452
	RMSE	8.5702	8.6054	8.9434	10.1524	7.1243	6.4368
12 days	MAE	8.3872	8.7682	8.4326	9.8170	5.6710	4.7166
	Accuracy	4.2830	4.8920	8.2192	8.5742	8.7246	9.1527
	R^2	3.7581	4.1268	7.3734	8.1289	8.4430	9.2721
	RMSE	8.2301	8.3436	8.5293	9.8425	6.2882	5.4397
18 days	MAE	8.3487	8.4018	7.7845	9.4696	4.4520	4.1625
	Accuracy	4.7557	4.8361	8.1395	8.5729	8.8314	9.0765
	R^2	3.3912	3.8852	8.3254	8.8772	8.7431	9.0293
	RMSE	8.2568	8.2578	8.2456	9.5742	4.5890	4.5174
24 days	MAE	8.1863	8.2146	7.6781	7.5682	4.1379	4.0764
	Accuracy	4.1732	4.5185	8.8563	8.9567	9.0137	9.2738
	R^2	3.2754	3.8571	8.3264	9.0753	8.1432	9.1432

tively. Considering that vertex features as follows.

$$
h_{v_i} = \begin{bmatrix} s_{1,1} & s_{1,2} & \cdots & s_{1,m} \\ s_{2,1} & s_{2,2} & \cdots & s_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ s_{n,1} & s_{n,2} & \cdots & s_{n,m} \end{bmatrix}
$$

Vertex v's neighbors $h_v^{l+1} = AGG{m_u^{l+1}, u \in N(v)}$ can be used to calculate the vertex embedding under the aggregation sum(.), where $l = 0, 1, 2, 3, ..., k$. $h_v^{l+1} = SUM{m_u^{l+1}, u \in$ $N(v)$, therefore, with regard to the matrix $B = A + 1$, where A, I denote the adjacency matrix and the identity matrix, respectively.

Proof. We can find the matrix adjacency A by graph G . Given that each vertex in G needs to consider the self adjacency, we must add A by the identity matrix I in order to get matrix B as follow.

$$
B = A + I = \begin{bmatrix} b_{1,1} & b_{1,2} & \cdots & b_{1,n} \\ b_{2,1} & b_{2,2} & \cdots & b_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n,1} & b_{n,2} & \cdots & b_{n,n} \end{bmatrix}
$$

The single layer STGNN technique requires that the learning weight matrix be initial-

T	Matric	HA	ARIMA	SVR	GCN	GRU	STGNN
	RMSE	10.7632	12.6281	10.8932	12.2971	13.8912	9.1378
6 days	MAE	10.4632	11.8714	10.1252	11.5318	11.6219	9.0374
	Accuracy	8.4778	9.6425	9.8687	10.3562	8.6315	10.6574
	$\,R^2$	7.0246	7.3526	9.3829	8.4912	7.0541	10.8831
	RMSE	10.4516	11.4354	9.8931	11.4871	11.2673	8.8576
$12 \;{\rm days}$	MAE	9.7320	11.9034	9.4965	11.2765	10.6490	8.6970
	Accuracy	8.1754	9.3292	9.8286	9.7605	9.0794	9.9521
	R^2	8.1642	7.3759	9.8342	8.7524	9.0836	9.9536
	RMSE	9.1765	11.5443	9.4870	10.8290	10.1230	8.9860
18 days	MAE	8.7662	10.2872	8.8267	10.6390	8.5503	8.0346
	Accuracy	8.2280	9.4782	9.1678	9.0894	7.1190	9.8570
	R^2	7.4581	7.3467	9.0340	8.4890	7.3095	9.3271
	RMSE	8.3604	10.5849	9.3235	10.7590	9.7208	8.2987
24 days	MAE	8.0045	10.2348	8.6903	10.6537	8.2782	7.5048
	Accuracy	8.1372	9.4573	9.2675	9.8362	7.7832	9.8653
	R^2	7.2670	7.4563	9.1703	8.2467	7.4561	9.5672

Table 2: The prediction results of STGNN model for dataset-2

ized in the way that is described below.

$$
W = \begin{bmatrix} w_{1,1} & w_{1,2} & \cdots & w_{1,m} \\ w_{2,1} & w_{2,2} & \cdots & w_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ w_{m,1} & w_{m,2} & \cdots & w_{m,m} \end{bmatrix}
$$

The value of m_{v_i} will be determined using this weight, and the new weight will be updated in the following iteration. There are two phases to the STGNN vertex embedding process: message passing and aggregation. First, we perform massage passing m_u = $MSG(h_u)$. For linear layer we have $m_u^{l+1} = W^l \cdot h_u^l$, where $l = 0, 1, 2, ...k$. The calculation can be started in an iterative manner as follows.

$$
m_{v_i}^1 = H_{v_i}^0 \cdot W^0 = \begin{bmatrix} s_{1,1} & s_{1,2} & \cdots & s_{1,m} \\ s_{2,1} & s_{2,2} & \cdots & s_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ s_{n,1} & s_{n,2} & \cdots & s_{n,m} \end{bmatrix} \times \begin{bmatrix} w_{1,1} & w_{1,2} & \cdots & w_{1,m} \\ w_{2,1} & w_{2,2} & \cdots & w_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ w_{m,1} & w_{m,2} & \cdots & w_{m,m} \end{bmatrix}
$$

$$
= \begin{bmatrix} s_{1,1} \times w_{1,1} + \ldots + s_{1,m} \times w_{m,1} & \ldots & s_{1,1} \times w_{1,m} + \ldots + s_{1,m} \times w_{m,m} \\ s_{2,1} \times w_{1,1} + \ldots + s_{2,m} \times w_{m,1} & \ldots & s_{2,1} \times w_{1,m} + \ldots + s_{2,m} \times w_{m,m} \\ \vdots & \vdots & \ddots & \vdots \\ s_{n,1} \times w_{1,1} + \ldots + s_{n,m} \times w_{m,1} & \ldots & s_{n,1} \times w_{1,m} + \ldots + s_{n,m} \times w_{m,m} \end{bmatrix}
$$

Following completion of the aforementioned process, we go on to the second phase, which is aggregation in regrads with v's neighbors. By ultilizing the aggregation $sum(.)$,

Figure 5: The companion farming layout based on b –Coloring theorem

Figure 6: The illustration of companion farming using b−Coloring

for $h_v^{l+1} = AGG{m_u^{l+1}, u \in N(v)}$ we have $h_v^{l+1} = SUM{m_u^{l+1}, u \in N(v)}$ in regrads to the matrix $B = A + 1$, the embedding vector $h_{v_i}^1$ can compose as follows.

$$
h_{v_i}^{l+1} = \begin{bmatrix} m_{v_{1,1}}^{l+1} & m_{v_{1,2}}^{l+1} & \cdots & m_{v_{1,m}}^{l+1} \\ m_{v_{2,1}}^{l+1} & m_{v_{2,2}}^{l+1} & \cdots & m_{v_{2,m}}^{l+1} \\ \vdots & \vdots & \ddots & \vdots \\ m_{v_{n,1}}^{l+1} & m_{v_{n,2}}^{l+1} & \cdots & m_{v_{n,m}}^{l+1} \end{bmatrix}
$$

The next step is to determine the error value, which shows how near two neighboring vertices are to one another in the embedding space. The separation of the two vertices gets smaller as the error value decreases. One can formulate the error as follows: $error^l =$ $\frac{h(v_i)-h(v_j)_{inf}}{|E(G)|}$ where $i, j \in \{1, 2, ..., n\}$. We need to check whether $error \leq \epsilon$. If no, we need to update new W^l using the obtained $h_{v_i}^l$ in the previous iteration. We revise the matrix of learning weights by using $W^{l+1} = W^l + \alpha \times error^l \times (h_{v_i}^l)^T \times h_{v_i}^{l+1}$ until $error \leq \epsilon$.

3.4. The Performance of STGNN Training and Testing

Furthermore, a computer simulation of the STGNN architecture will be carried out for training, testing, and forecasting companion farming data using the one-layer STGNN algorithm. Then analyzed soil moisture and pH at 64 planting vertex on the graph $P_n \triangleright_{v_1}$ P_m . The first stage of this research performs the process of vertex embedding of single layer STGNN on the given graph with 2 data features, namely soil moisture and pH data for 30 days of observation. Overall, the data consists of $64 \times 2 \times 30 = 3840$, which consists of 64 planting vertex, two features and 30 days of observation. The data is obtained from several soil sensors placed in one of the companion planting.

After performing the algorithm above, the adjacency matrix of the graph $P_n \triangleright_{v_1} P_m$ can be seen in Figure 7. Furthermore, the distribution graph of soil moisture and pH with 64 planting vertex for 30 days is shown in Figure 8. The results of training and testing of companion farming at 64 planting vertex are shown in Figure 9. After that, the results of the multi-step time series forecasting graph for the next 6 days are shown in Figure 10.

Figure 7: $P_n \triangleright_{v_1} P_m$ graph with 64 vertices and companion farming adjacency matrix

Figure 8: The distribution of soil moisture, temperature and pH with 64 companion farming vertex on 30 days to training and testing dataset

Based on the previously described algorithm, an vertex embedding with 64 planting vertices is required. In the process of message passing, it assumes that each vertex has some information and sends the information to its neighbours. With the above algorithm steps,

Figure 9: The result of training and testing data of companion farming

Figure 10: The result of multi-step time series forecasting of companion farming

time series data is obtained to be analyzed using STGNN. To consider how effective the result of vertex embedding is, next determine the error by considering every two adjacent vertices. Then, a multi-step time series prediction algorithm is developed. STGNN to train 60% of the data and obtain the smallest Root Mean Square Error (RMSE) and Mean Square Error (MSE) of the test data. After the algorithm of soil moisture and p H data, the MSE value obtained on the planting layout $P_n \triangleright_{v_1} P_m$ is 0.0267. To convince the robustness of the STGNN model, we compare six models, namely historical average (HA), auto regressive integrated moving average (ARIMA), support vector regression (SVR), graph convolutions networks (GCN), gated recurrent unit (GRU), spatial temporal graph neural networks (STGNN) can be seen in Table 1 and Table 2. The STGNN model also shows that time series forecasting for 6, 12, 18, 24 days ahead, either RMSE, MAE, Accuracy and R^2 show the best values compare with other models. The STGNN model shows the best forecasting for 6, 12, 18, 24, days ahead, both RMSE, MAE, Accuracy and

 $R²$. It also shows the best value of STGNN compared to other models. Thus, it can be concluded that the STGNN model can be used to perform forecasting and monitoring at 64 planting vertices using b−Coloring.

4. Concluding Remarks

In this research, we have studied b−Coloring of graphs. We have determined the exact value of the b-chromatic number of $P_n \rhd_{v_1} P_m$ graph for $n, m \geq 8$ and $L_n \rhd_{v_1} P_m$ graph for $n, m \geq 5$. We found the b-chromatic numbers attain the best upper bound. However, since there is currently little research on the topic of b–Coloring, we propose the open problem. Find the exact values of b−Coloring on other graphs and apply the obtained results in STGNN time series forecasting.

Acknowledgements

We gratefully acknowledge the support from PUI-PT Combinatorics, Graph Theory and Network Topology and LP2M University of Jember of year 2024.

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