EUROPEAN JOURNAL OF PURE AND APPLIED MATHEMATICS

Vol. 17, No. 4, 2024, 3660-3676 ISSN 1307-5543 – ejpam.com Published by New York Business Global

Additional Studies on Displacement Mapping with Restrictions

Salihah Thabet Alwadani

Mathematics, Yanbu Industrial College, The Royal Comission for Jubail and Yanbu, Yanbu, Saudi Arabia

Abstract. The theory of monotone operators is fundamental in modern optimization and various areas of nonlinear analysis. Key classes of monotone operators include matrices with a positive semidefinite symmetric component and subdifferential operators. In this paper, we extend our investigation to displacement mappings. We derive formulas for set-valued and Moore-Penrose inverses. Additionally, we conduct a thorough examination of the operators (one-half times the identity plus *T*) and its inverse, providing a formula for the inverse of the operator. Our results are illustrated through an analysis of reflected and projection operators onto closed linear subspaces.

2020 Mathematics Subject Classifications: 47H09, 47H05, 47A06, 90C25

Key Words and Phrases: Displacement mapping, maximally monotone operator, nonexpansive mapping, , Moore-Penrose inverse set-valued inverse, inverse, Yosida approximation

1. Introduction

It is well known that one of important classes of monotone operators are Displacement mappings of nonexpansive mappings. There are many key examples that have proven how these mappings are highly useful in optimization problems. For example, in 2016 Heinz H. Bauschke, Warren Hare, and Walaa Moursi used displacement mappings in analyzing the range of the Douglas–Rachford operator to derive valuable duality results, see [5]. Additionally, the asymptotic regularity results for nonexpansive mappings were generalized in [8] to the broader context of displacement mappings. Overall, the displacement mapping framework has emerged as a powerful tool for analyzing the behavior of nonexpansive mappings, with a range of important applications in optimization and related areas. Throughout, we assume that

X is a real Hilbert space with inner product $\langle \cdot, \cdot \rangle : X \times X \to \mathbb{R}$, (1)

https://www.ejpam.com 3660 Copyright: © 2024 The Author(s). (CC BY-NC 4.0)

DOI: https://doi.org/10.29020/nybg.ejpam.v17i4.5504

Email address: salihah.s.alwadani@gmail.com (S. T. Alwadani)

and induced norm $\|\cdot\| \colon X \to \mathbb{R} \colon x \mapsto \sqrt{\langle x, x \rangle}$. We also assume that $A : X \rightrightarrows X$ and $B: X \rightrightarrows X$ are maximally monotone operators. The *resolvent* and the *reflected resolvent* associated with *A* are

$$
J_A = (\text{Id} + A)^{-1} \text{ and } R_A = 2J_A - \text{Id}, \tag{2}
$$

respectively. An operator $T : X \rightrightarrows X$ is *nonexpansive* if it is Lipschitz continuous with constant 1, i.e.,

$$
(\forall x \in X)(\forall y \in X) \|Tx - Ty\| \leq \|x - y\|.
$$
 (3)

Moreover, $T : D \rightrightarrows X$ is *firmly nonexpansive* if

$$
(\forall x \in D)(\forall y \in D) \|Tx - Ty\|^2 + \|(Id - T)x - (Id - T)y\|^2 \le \|x - y\|^2. \tag{4}
$$

Fact 1. [4, Definition 4.10] Let D be a nonempty subset of X, let $T : D \to X$, and let $\beta \in \mathbb{R}_{++}$, *where* \mathbb{R}_{++} *is the set of strictly positive real numbers* $\vert 0, +\infty \vert$. Then T *is β*-cocoercive (or *βinverse strongly monotone) if βT is firmly nonexpansive, i.e.,*

$$
(\forall x \in D)(\forall y \in D) \quad \langle x - y, Tx - Ty \rangle \ge \beta ||Tx - Ty||^2.
$$

In optimization, we have seen the importance the *displacement mappings* of nonexpansive mappings:

$$
Id - R \tag{5}
$$

because of the nice properities that have such as monotonicity which plays a central role in modern optimization (see [4, 11, 18, 20–23] for more details). A comprehensive analysis of the displacement mappings of nonexpansive mappings from the point of view of monotone operator theory under the condition of isometry of finite order of *R* are given in [2, Lemma] and [1, Section 3]. We refer the reder to [18, Exercise 12.16], and [4, Example 20.29], [7]. More information is in [10, 15, 17, 19].

Throughout this paper, we assume that

$$
R: X \to X
$$
 is linear and nonexpansive, with $D := Fix R = ker (Id - R)$. (6)

In this paper, we study the displacement mapping using the assumption in (6). Our results can be summarized as follows

- Proposition 1, Lemma 1, and Remark 1 collect some useful properities of the dispdisplacment mapping and its inverse, which will be useful in our study.
- Lemma 2 provides a formula and gives nice properties of the operator *T*.
- We derive a formula for the inverse of the displacment mapping (see Theorem 2 (i)). A formula for the Moore-Penrose inverse of the displacement mapping is given in Theorem 2(ii).

- Theorem 3 gives a comprehensive study of the the operators $(1/2)$ Id $+T$ and its inverse. Additionaly, we derive a formula of $\Big(\,(1/2)\, \mathrm{Id} + T\Big)^{-1}$ and prove that is equal to the resolvant of the operator 2*T*.
- We illustrates the reults by giving four examples. The first two examples are related to the projection operator to a closed linear subspace (see Example 2 and Example 3), while the other two are related to the reflected operator to closed linear subspace (see Example 4 and Example 5).

2. Results

Important properties of the displacement mapping (Id −*R*) and its inverse are given in the next proposition.

Proposition 1. *Let R be nonexpansive operator, then the following holds:*

- (i) $\frac{1}{2}$ (Id −*R*) *is firmly nonexpansive.*
- *(ii)* Id −*R is nonexpansive.*
- *(iii)* Id $-R$ and $(Id R)^{-1}$ are maximally monotone.
- *(iv)* Id −*R is* $\frac{1}{2}$ -cocoercive.
- *(v)* $(\text{Id} R)^{-1}$ *is strongly monotone*^{*}*with constant* $\frac{1}{2}$ *.*
- *(vi)* Id −*R is* 3 [∗] *monotone.*
- *(vii)* (Id −*R*) −1 *is* 3 [∗] *monotone*
- *(viii)* Id −*R is paramonotone.*
- (ix) $(Id R)$ ⁻¹ − $\frac{1}{2}$ Id *is maximally monotone.*

Proof. (i): We have

R is nonexpansive \Leftrightarrow $-R = 2((Id - R)/2)$ is nonexpansive ⇔ Id −*R* /2 is firmly nonexpansive,

by [4, Proposition 4.4]. (ii): It follows from (i) and [4, Proposition 4.2] . (iii): See [4, Example 25.20(v)] or [2, Theorem 7.1]. (iv): Combine (i) and Fact 1. (v): Take $(x, u) \in$ $\text{gra}(\text{Id}-R)^{-1}$ and $(y, v) \in \text{gra}(\text{Id}-R)^{-1}$. Then $u \in (\text{Id}-R)^{-1}x \Rightarrow x = u - Ru$ and $v \in (\text{Id}-R)^{-1}y \Rightarrow y = v - Rv.$

$$
\langle u-v, x-y \rangle \ge \frac{1}{2} ||x-y||^2
$$

\n
$$
\Leftrightarrow \langle u-v, (u-Ru) - (v-Rv) \rangle \ge \frac{1}{2} ||(u-Ru) - (v-Rv) ||^2,
$$

[∗]An operator *A* : *X* \Rightarrow *X* is strongly monotone with constant *β* ∈ **R**₊₊ if *A* − *β* Id is montone, i.e.,

$$
(\forall (x, u) \in \text{gra } A)(\forall (y, v) \in \text{gra } A) \quad \langle x - y, u - v \rangle \ge \beta \|x - y\|^2.
$$

which deduce from (iv) and Footnote $*$ that $(\text{Id} - R)^{-1}$ is strongly monotone with constant (1/2). (vi) and (vii): It follows from (iv) that Id −*R* is bounded by (1/2) and its monotone by (iii). Hence, Id $-R$ and $(\text{Id}-R)^{-1}$ are 3^{*} monotone by [4, Proposition 25.16(i) & (iv)].

(viii): See [4, Example 22.9]. (ix): By (iv) and [4, Example 22.7], $(\text{Id}-R)^{-1}$ is $(1/2)$ strongly monotone, i.e., $B := (\text{Id} - R)^{-1} - \frac{1}{2} \text{Id}$ is still monotone. If *B* was not maximally monotone, then neither would be $B + \frac{1}{2}$ Id = $(\text{Id}-R)^{-1}$ which would contradict (iii). ■

Lemma 1. *Set* $D := \text{ker} (Id - R) = \text{Fix } R$. *Then the following holds:*

- *(i) D is a closed linear subspace.*
- (ii) Fix $R^* = D$.
- (iii) $\overline{\text{ran}} (\text{Id} R) = \overline{\text{ran}} (\text{Id} R^*) = D^{\perp}.$

Proof. (i): Let $x, y \in D$ such that $x - Rx = 0$ and $y - Ry = 0$. Let $\alpha, \beta \in \mathbb{R}$. Then

$$
(Id - R) (\alpha x + \beta y) = (Id - R) (\alpha x) + (Id - R) (\beta y)
$$

= $\alpha (x - Rx) + \beta (y - Ry)$
= 0 + 0 = 0.

Therefore, $\alpha x + \beta y \in D$ and hence *D* is a linear subspace. To show that *D* is closed, let (x_n) be a sequence in *D* such that (x_n) converges to *x*. Then

$$
\lim_{n \to \infty} (\text{Id} - R)(x - x_n) = \lim_{n \to \infty} (\text{Id} - R)x - \lim_{n \to \infty} (\text{Id} - R)x_n
$$

$$
= (\text{Id} - R)x - (\text{Id} - R)x = 0.
$$

Therefore, $x \in D$ and hence *D* is closed.

(ii) and (iii): It follows from Proposition 1(iii) & (iv) that Id −*R* is monotone and bounded. Hence, Fix $R^* =$ Fix $R = D$ and $\overline{ran} (Id - R) = \overline{ran} (Id - R^*) = D^{\perp}$ by [4, Proposi- $\frac{1}{2}$ tion 20.17].

Remark 1. *Suppose that* $X = \ell_2(\mathbb{N})$ *and that*

$$
R: X \to X: (x_n)_{n \in \mathbb{N}} \mapsto (((1 - \varepsilon_n) x_n))_{n \in \mathbb{N'}} \tag{7}
$$

where $(\varepsilon_n)_{n \in \mathbb{N}}$ *lies in* $]0,1[$ *with* $\varepsilon_n \to 0$ *. Then the following holds:*

- *(i)* Id −*R* : $(x_n)_{n \in \mathbb{N}}$ \mapsto $(\varepsilon_n x_n)_{n \in \mathbb{N}}$ *is a compact operator.*
- *(ii)* $D = Fix R = \{0\}.$
- *(iii)* ran (Id −*R*) *is not closed.*
- *(iv)* ran *R is a closed subspace.*

Proof. (i) and (ii): See [12, PropositionII.4.6]. (iii): It follows from [16, Proposition 3.4.6] that ran (Id −*R*) is closed if and only if ran (Id −*R*) is finite-dimensional. On the other hand, $X = D^{\perp} = \overline{ran}(Id - R)$, i.e., the range of Id −*R* is dense in the infinite-dimensional space *X*. Altogether,

$$
ran
$$
 ($Id - R$) is not closed.

 $(iv):$ See [16, Lemma 3.4.20].

Lemma 2. *Suppose that* ran (Id −*R*) *is closed; equivalently,*

$$
ran (Id - R) = D^{\perp}.
$$

Set

$$
T := P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}.
$$
 (8)

Then,

- *(i)* ran $(Id R)^* = D^{\perp}$ *.*
- *(ii) T is a linear and continuous.*
- *(iii) T is monotone.*
- *(iv) T is maximally monotone.*
- *(v)* ran *T* ⊆ *D*[⊥]*, where D* = ker(Id −*R*)*.*
- *(vi)* $P_{D^{\perp}}$ *T* = *T* $P_{D^{\perp}}$ = *T*.

Proof. (i): By using the closeness of ran (Id −*R*) and ...

$$
ran (Id - R)^* = ran (Id - R^*)
$$

= ran (Id - R)
= D^{\perp} .

(ii): This is clear because *T* is defined using $P_{D^{\perp}}$, which is a linear and continuous operator. (iii): See [4, Example 20.12]. (iv): Combine (ii), (iii) and [4, Corollary 20.28]. (v): It follows directly from (8). (vi): Since ran $T \subseteq D^{\perp}$ by using (v), we obtain

$$
\mathbf{P}_{D^{\perp}}\,T=T.
$$

Moreover, both *T* and $P_{D^{\perp}}$ commute and so

$$
T\,{\bf P}_{D^\perp}={\bf P}_{D^\perp}\,T=T.
$$

Remark 2. *It is well known that* ran (Id −*R*) *is closed if and only if there exists α* > 0 *such that*

$$
\left(\forall y \in (\ker(\text{Id}-R))^\perp = D^\perp\right) \|y - Ry\| \ge \alpha \|y\|; \tag{9}
$$

Proof. See [13, Theorem 8.18]. ■

Proposition 2. *Suppose that* (9) *holds, then the operator*

$$
P_{D^{\perp}}(\text{Id}-R)^{-1}: D^{\perp} \to D^{\perp}, \tag{10}
$$

- *(i) is a linear selection of* T^{-1} *.*
- *(ii) is continuous and its norm is bounded above by* 1/*α.*

Proof. (i): It follows from (8) and Lemma 2. (ii): Clear from (9). ■

Theorem 1. *Suppose that* ran (Id −*R*) *is closed. Set*

$$
A := (\text{Id} - R)^{-1} - \frac{1}{2} \text{Id},\tag{11}
$$

and defined

$$
Q_A: \text{dom } A \to X: y \mapsto P_{Ay} y. \tag{12}
$$

Set

$$
B := P_{\text{dom }A} Q_A P_{\text{dom }A}.
$$
 (13)

Then the following holds;

- *(i)* dom $A = D^{\perp}$ *and is closed.*
- *(ii) A is linear relation.*
- *(iii) A is maximally monotone.*
- *(iv) we have*

$$
(\forall y \in \text{dom } A) \ Q_A y = P_{D^{\perp}} (\text{Id} - R)^{-1} y - \frac{1}{2} P_{D^{\perp}} y.
$$

- *(v) B is maximally monotone, linear and continuous.*
- (vi) *A* = $N_{D^{\perp}}$ + *B*.
- (vii) $B = T$.
- *(viii)* $B|_{\text{dom } A}$ *is a selection of* $A|_{\text{dom } A}$ *.*

Proof. (i): From (11) dom *A* = ran (Id $-R$) = D^{\perp} , which is closed by the assumption. (ii): It is clear that *A* is a linear relation, i.e., gra *A* is a linear subspace, that $A0 = D$, and by (i) the dom $A = D^{\perp}$ is closed.

(iii): It follows directly from Proposition 1(ix).

(iv): By [9, Proposition 6.2], we have $(\forall y \in \text{dom } A) Q_A y = P_{(A0)^{\perp}}(Ay) \in Ay$. Hence,

$$
(\forall y \in D^{\perp}) \ Q_A y = P_{D^{\perp}}(Ay) = P_{D^{\perp}} \left((\text{Id} - R)^{-1} y - \frac{1}{2} y \right)
$$

$$
= P_{D^{\perp}} (\text{Id} - R)^{-1} y - \frac{1}{2} P_{D^{\perp}} y.
$$

(v): See [9, Example 6.4(i)]. (vi): Combining (i) and [9, Example 6.4(iii)] gives

$$
A = N_{\text{dom }A} + B = N_{D^{\perp}} + B.
$$

(vii): Using (13), (iv) and (i) gives

$$
B = P_{\text{dom }A} Q_A P_{\text{dom }A}
$$

= $P_{D^{\perp}} (P_{D^{\perp}} (\text{Id} - R)^{-1} - \frac{1}{2} P_{D^{\perp}}) P_{D^{\perp}}$
= $P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}$

$$
=T \quad \text{(from (8))}.
$$

(viii): Using (i) gives

$$
A|_{\text{dom }A} = (N_{D^{\perp}} + B)|_{D^{\perp}} \text{ (from (vi))}
$$

= $(N_{D^{\perp}} + T)|_{D^{\perp}} \text{ (from (vii))}$
= $(N_{D^{\perp}} + P_{D^{\perp}}(\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}})|_{D^{\perp}} \text{ (from (8))}$
 $\equiv D + D^{\perp} \text{ (because } N_{D^{\perp}}|_{D^{\perp}} \equiv D),$

and

$$
B|_{\text{dom } A} = T|_{D^{\perp}} \text{ (from (i) and (vii))}
$$

= $\left(P_{D^{\perp}} (\text{Id } -R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}} \right)\Big|_{D^{\perp}}$ (from (8))
= D^{\perp} .

Hence, $B|_{\text{dom } A}$ is a selection of $A|_{\text{dom } A}$. ■

In the next theorem we derive formulas for the inverse and Moore-Penrose inverse of the operator $(Id - R)$.

Theorem 2. *Recall from* (8) *and* (11) *that*

$$
T := P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}},
$$

and

$$
A := (\text{Id} - R)^{-1} - \frac{1}{2} \text{Id},
$$

respectively.Then the following holds;

(i) The set-valued inverse of Id −*R is*

$$
(\text{Id} - R)^{-1} = \frac{1}{2} \text{Id} + T + N_{D^{\perp}}.
$$
 (14)

(ii) The Moore-Penrose inverse of Id −*R is*

$$
(\text{Id} - R)^{\dagger} = T + \frac{1}{2} P_{D^{\perp}}.
$$
 (15)

Proof. (i): Combining Theorem 1(vi) & (vii) and (11) gives

$$
(\text{Id} - R)^{-1} - \frac{1}{2} \text{Id} = A
$$

= $N_{D^{\perp}} + T$,

Hence,

$$
(\text{Id}-R)^{-1} = N_{D^{\perp}} + T + \frac{1}{2} \text{Id}.
$$

(ii): By using [6, Proposition 2.1] and we obtain

$$
(\text{Id} - R)^{\dagger} = P_{(\text{Id} - R)^*} \circ (\text{Id} - R)^{-1} \circ P_{\text{ran}(\text{Id} - R)}
$$

\n
$$
= P_{D^{\perp}} \circ (\text{Id} - R)^{-1} \circ P_{D^{\perp}} \text{ (from Lemma 2(i))}
$$

\n
$$
= P_{D^{\perp}} \circ \left(\frac{1}{2} \text{Id} + T + N_{D^{\perp}}\right) \circ P_{D^{\perp}} \text{ (from (i))}
$$

\n
$$
= P_{D^{\perp}} \circ \left(\frac{1}{2} P_{D^{\perp}} + T P_{D^{\perp}} + D\right) \text{ (Because } N_{D^{\perp}}|_{D^{\perp}} \equiv D)
$$

\n
$$
= \frac{1}{2} P_{D^{\perp}} + P_{D^{\perp}} T P_{D^{\perp}} + 0
$$

\n
$$
= \frac{1}{2} P_{D^{\perp}} + T \text{ (from Lemma 2(vi))},
$$

which verified (15). ■

Proposition 3 (uniqueness of *T*). Let T_o : $X \rightarrow X$ be such that

$$
(\text{Id} - R)^{-1} = \frac{1}{2} \text{Id} + T_{\circ} + N_{D^{\perp}}, \tag{16}
$$

and

$$
P_{D^{\perp}} T_{\circ} P_{D^{\perp}} = T_{\circ}. \tag{17}
$$

Then $T_{\circ} = T$ *.*

Proof. By using (8), we have

$$
T = P_{D^{\perp}} (Id - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}
$$

= $P_{D^{\perp}} \left(\frac{1}{2} Id + T_{\circ} + N_{D^{\perp}} \right) P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}$ (from (16))
= $P_{D^{\perp}} T_{\circ} P_{D^{\perp}}$
= T_{\circ} (from (17)),

as claimed.

Theorem 3. *Recall from* (8) *that*

$$
T = P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}.
$$

Then the following holds;

- *(i)* $(1/2)$ Id $+T$ *is* $\frac{1}{2}$ -strongly monotone.
- (*ii*) $((1/2)\text{Id} + T)^{-1} = 2J_{2T}$.

 (iii) 2*T* + Id = 2 $P_{D^{\perp}}$ (Id −*R*)⁻¹ $P_{D^{\perp}}$ + P_{D} *.* $(i\upsilon)$ $J_{2T} = P_D + \frac{1}{2}(\text{Id} - R) P_{D^{\perp}}.$ *(v)* $2J_{2T}$ = (Id −*R*) $P_{D^{\perp}}$ +2 P_{D} *. (vi)* $(\text{Id} - R) P_{D^{\perp}} + 2 P_{D} = \text{Id} - R + 2 P_{D}$ *. (vii) We have* (1) $\frac{1}{2}$ Id + T)⁻¹ = 2*J*_{2*T*} = (Id - *R*) P_{*D*[⊥] +2 P_{*D*} = Id - *R* + 2 P_{*D*}. (18)} (*viii*) $\left(\frac{1}{2}\right)$ $\frac{1}{2}$ **I**d + *T*)⁻¹ $\Big|_{D^{\perp}}$ $=$ Id $-R$.

Proof. (i): Showing that $\frac{1}{2}$ Id + *T* is (1/2)-strongly monotone $\Leftrightarrow \frac{1}{2}$ Id + *T* $\frac{1}{2}$ Id = *T* is montone, which is verified by Lemma 2(iii). (ii): From Lemma 2(ii) & (iv) and [14, Lemma 2], we have

$$
\left(\frac{1}{2}\operatorname{Id} + T\right)^{-1} = \left(\frac{1}{2}(\operatorname{Id} + 2T)\right)^{-1} \\
= 2(\operatorname{Id} + 2T)^{-1} \\
= 2J_{2T}.
$$

(iii): By using (8) and Lemma 2(ii), we obtain

$$
2T = 2\left(P_{D^{\perp}}(\text{Id}-R)^{-1}P_{D^{\perp}} - \frac{1}{2}P_{D^{\perp}}\right)
$$

= 2P_{D^{\perp}}(\text{Id}-R)^{-1}P_{D^{\perp}} - P_{D^{\perp}},

hence

$$
2T + Id = 2P_{D^{\perp}}(Id - R)^{-1}P_{D^{\perp}} - P_{D^{\perp}} + Id
$$

=
$$
2P_{D^{\perp}}(Id - R)^{-1}P_{D^{\perp}} + P_{D}.
$$

(iv): From (iii), we obtain $2T + Id = 2P_{D^{\perp}}(Id - R)^{-1}P_{D^{\perp}} + P_D$. Put differently,

$$
2T + \text{Id}: D \oplus D^{\perp} \to D \oplus D^{\perp}: d \oplus d^{\perp} \mapsto d + 2P_{D^{\perp}}(\text{Id}-R)^{-1}d^{\perp}.
$$

For two vectors d^\perp , e^\perp in D^\perp , we have the equivalences,

$$
e^{\perp} = 2 P_{D^{\perp}} (\text{Id} - R)^{-1} d^{\perp} \Leftrightarrow d^{\perp} = \left(2 P_{D^{\perp}} (\text{Id} - R)^{-1} \right)^{-1} e^{\perp},
$$

and therefore,

$$
d^{\perp} = (2 P_{D^{\perp}} (\text{Id} - R)^{-1})^{-1} e^{\perp}
$$

= $(2 (P_{D^{\perp}} (\text{Id} - R)^{-1}))^{-1} e^{\perp}$

$$
= \frac{1}{2} \left(P_{D^{\perp}} (\text{Id} - R)^{-1} \right)^{-1} e^{\perp}
$$

= $\frac{1}{2} (\text{Id} - R) P_{D^{\perp}}^{-1} e^{\perp}$
= $\frac{1}{2} (\text{Id} - R) e^{\perp}.$

Hence,

$$
(2T + \mathrm{Id})^{-1}: D \oplus D^{\perp} \to D \oplus D^{\perp}: d \oplus d^{\perp} \mapsto d + \frac{1}{2}(\mathrm{Id} - R)d^{\perp};
$$

equivalently,

$$
J_{2T} = (2T + \text{Id})^{-1} : z \mapsto P_D z + \frac{1}{2} (\text{Id} - R) P_{D^{\perp}} z.
$$

(v): It follows directly from (iv). (vi): Because ker(Id $-R$) = *D*, we have (Id $-R$) $P_D \equiv 0$. Therefore,

$$
(\mathrm{Id}-R)P_{D^{\perp}}+2P_D=\mathrm{Id}-R+2P_D.
$$

(vii): Combine (ii), (v), and (vi). (viii): From (v), we obtain

$$
\left(\frac{1}{2}\operatorname{Id} + T\right)^{-1}\Big|_{D^{\perp}} = \left(\operatorname{Id} - R + 2P_D\right)\Big|_{D^{\perp}} = \operatorname{Id} - R.
$$

Proposition 4. Let $m \in \{2, 3, ...\}$ and assume that $R^m = \text{Id}$, i.e., R is an isometry of finite *rank m. Assume that* $X = R^m$ *and recall from [2, Lemma] that*

$$
P_D = \frac{1}{m} \sum_{k=0}^{m-1} R^k \quad \text{and} \quad P_{D^{\perp}} = \text{Id} - \frac{1}{m} \sum_{k=0}^{m-1} R^k,
$$
 (19)

where $D = Fix R$ *. Then*

$$
\frac{1}{2}P_{D^{\perp}}\left(R+R^{*}\right)P_{D^{\perp}}=\frac{1}{m}\left(-\operatorname{Id}-\sum_{k=2}^{m-2}R^{k}+\frac{\max\{1,m-2\}}{2}\left(R+R^{m-1}\right)\right).
$$
 (20)

Proof. Noted that *R* is an isometry \Rightarrow $R^*R = RR^* = Id$, so $R^{-1} = R^*$. But also *R* has rank m , hence $R^{m-1} = R^{-1} = R^*$. By using these facts, we obtain

$$
P_{D^{\perp}}(R + R^*) P_{D^{\perp}} = P_{D^{\perp}}(R + R^{-1}) P_{D^{\perp}}
$$

= $P_{D^{\perp}}(R + R^{-1}) \Big(\text{Id} - \frac{1}{m} \sum_{k=0}^{m-1} R^k \Big) \quad \text{(from (19))}$
= $P_{D^{\perp}} \Big((R + R^{-1}) - \frac{1}{m} \sum_{k=0}^{m-1} (R + R^{-1}) R^k \Big)$
= $P_{D^{\perp}} \Big((R + R^{-1}) - \frac{1}{m} \sum_{k=0}^{m-1} (R^{k+1} + R^{k-1}) \Big).$

Since *R* has rank *m*, the following holds:

$$
\sum_{k=0}^{m-1} R^{k+1} = \sum_{k=0}^{m-1} R^{k-1} = \sum_{k=0}^{m-1} R^k.
$$
 (21)

Moreover,

$$
R^l \sum_{k=0}^{m-1} R^k = \sum_{k=0}^{m-1} R^{l+k} = \sum_{k=0}^{m-1} R^k
$$
 (22)

Thus,

$$
(R + R^{-1}) \left(\frac{1}{m} \sum_{k=0}^{m-1} R^k\right) = \frac{1}{m} \sum_{k=0}^{m-1} \left(R^{k+1} + R^{k-1}\right) = \frac{2}{m} \sum_{k=0}^{m-1} R^k.
$$
 (23)

Therefore,

$$
P_{D^{\perp}}(R + R^{*}) P_{D^{\perp}} = P_{D^{\perp}} \left((R + R^{-1}) - \frac{1}{m} \sum_{k=0}^{m-1} (R^{k+1} + R^{k-1}) \right)
$$

\n
$$
= P_{D^{\perp}} \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right)
$$

\n
$$
= \left(\text{Id} - \frac{1}{m} \sum_{k=0}^{m-1} R^{k} \right) \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right)
$$

\n
$$
= \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right) - \left(\frac{1}{m} \sum_{k=0}^{m-1} R^{k} \right) \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right)
$$

\n
$$
= \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right) - \left(\frac{2}{m} \sum_{k=0}^{m-1} R^{k} - \frac{2}{m^{2}} \sum_{l=0}^{m-1} R^{l} \sum_{k=0}^{m-1} R^{k} \right)
$$

\n
$$
= \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right) - \left(\frac{2}{m} \sum_{k=0}^{m-1} R^{k} - \frac{2}{m^{2}} \sum_{l=0}^{m-1} \sum_{k=0}^{m} R^{k} \right)
$$

\n
$$
= \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right) - \left(\frac{2}{m} \sum_{k=0}^{m-1} R^{k} - \frac{2m}{m^{2}} \sum_{k=0}^{m-1} R^{k} \right)
$$

\n
$$
= \left((R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^{k} \right) - \left(\frac{2}{m} \sum_{k=0}^{m-1} R^{k} - \frac{2
$$

First: assume that $m > 2$. Therefore, $\max\{1, m - 2\} = m - 2$. Then

$$
P_{D^{\perp}}(R+R^*) P_{D^{\perp}} = (R+R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^k
$$

$$
= \frac{2}{m} \left(\frac{m}{2} (R + R^{-1}) - \sum_{k=0}^{m-1} R^{k} \right)
$$

=
$$
\frac{2}{m} \left(\left(\frac{m}{2} - 1 \right) (R + R^{-1}) - \mathrm{Id} - \sum_{k=2}^{m-2} R^{k} \right)
$$

=
$$
\frac{2}{m} \left(-\mathrm{Id} + \frac{m-2}{2} (R + R^{m-1}) - \sum_{k=2}^{m-2} R^{k} \right),
$$

which prove (20) when $m > 2$.

Next, assume that $m = 2$. Then $\max\{1, m-1\} = 1$ and $R^{-1} = R^{2-1} = R$. Therefore,

$$
P_{D^{\perp}}(R + R^*) P_{D^{\perp}} = (R + R^{-1}) - \frac{2}{m} \sum_{k=0}^{m-1} R^k
$$

= 2R - \frac{2}{2} (Id + R)
= 2R - Id - R
= R - Id.

On the other hand,

$$
\frac{2}{m} \left(-\operatorname{Id} + \frac{\max\{1, m-2\}}{2} (R + R^{m-1}) - \sum_{k=2}^{m-2} R^k \right) = \frac{2}{2} \left(-\operatorname{Id} + \frac{1}{2} (R + R) - \sum_{k=2}^0 R^k \right)
$$

$$
= -\operatorname{Id} + \frac{1}{2} (2R) - 0
$$

$$
= -\operatorname{Id} + R,
$$

so equality holds when $m = 2$.

3. Examples

Example 1 (isometry of finite rank). Let $m \in \{2, 3, \ldots\}$ and assume that

$$
R^m = \mathrm{Id} \,. \tag{24}
$$

Then the results in Section 2 were derived already in [1]. Moreover, the work there based on exploiting (24) *yielded to* (19) *and*

$$
T = \frac{1}{2m} \sum_{k=1}^{m-1} (m - 2k) R^k = -T^*,
$$
 (25)

which is always skew right-shift operator, T is symmetric only when $m = 2$ *.*

Example 2. *Let U be a closed subspace of X and suppose that*

$$
R = P_U. \t\t(26)
$$

Then

- (i) $D = U$. *(ii)* Id −*R* = P _{*U*[⊥]}.
- *(iii)* ran $(\text{Id} R)$ = D [⊥] *is closed.*
- (iv) $(\text{Id} R)^{-1} = \text{Id} + N_U.$
-
- $\left(\begin{matrix} v \end{matrix}\right) \; T = \frac{1}{2} \, \mathrm{P}_{U^{\perp}} = T^*.$
- *(vi)* T *is always symmetric, but skew only when* $U = X$.

Proof. (i): $D = Fix R = Fix P_U = \{x \in X \mid x = P_U x\} = U$. (ii): Id $-R = Id - P_U = P_{U^{\perp}}$. (iii): By using (ii), we obtain ran $(\text{Id} - R) = \tan (\text{Id} - P_U) = U^{\perp} = D^{\perp}$. (iv): From [4, Example 1], we have $(\text{Id} - R)^{-1} = (\text{Id} - P_U)^{-1} = P_{U^{\perp}}^{-1} = \text{Id} + N_{U^{\perp}}.$ (v): By using (8), we have

$$
T = P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}
$$

= $P_{U^{\perp}} (\text{Id} + N_{U^{\perp}}) P_{U^{\perp}} - \frac{1}{2} P_{U^{\perp}}$
= $\frac{1}{2} P_{U^{\perp}}$
= T^* .

 (vi) : Follows from (v) .

Example 3. *Let U be a closed subspace of X and suppose that*

$$
R = -P_U. \t\t(27)
$$

Then

(i) $D = \{0\}$. *(ii)* Id $-R = Id + P_U$. *(iii)* ran (Id −*R*) = *X .* (iv) $(\text{Id} - R)^{-1} = \frac{1}{2} \text{Id} + \frac{1}{2} P_{U^{\perp}}.$ (*v*) $T = \frac{1}{2} P_U$.

Proof. (i): *D* = Fix $R = Fix(-P_U) = \{x \in X \mid x = -P_U x\} = \{0\}$. (ii): Id $-R = Id + P_U$. (iii): By [4, Minty Theorem], $Id + P_U$ has full range $D = X$. (iv): $(\text{Id} - R)^{-1} = J_{P_U} =$ 1 $\frac{1}{2}$ P_U + P_U⊥ = $\frac{1}{2}$ Id + $\frac{1}{2}$ P_U⊥. (v): We have

$$
T = P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}
$$

= $\frac{1}{2} \text{Id} + \frac{1}{2} \text{Id} - \frac{1}{2} P_{U^{\perp}} - \frac{1}{2} \text{Id}$

 $=\frac{1}{2}$ $\frac{1}{2}P_U$.

Example 4. *Let U be a closed subspace of X and suppose that*

$$
R = R_U. \tag{28}
$$

Then

 (i) $D = U$. *(ii)* Id $-R = 2P_{U^{\perp}}$. *(iii)* ran $(\text{Id} - R) = D^\perp$ *is closed.* (iv) $(\text{Id} - R)^{-1} = \frac{1}{2} \text{Id} + N_U.$ (v) *T* = 0.

Proof. (i): $D = Fix R = Fix(R_U) = \{x \in X \mid x = R_U x\} = \{x \in X \mid 2x = 2P_U\} = U$. (ii): Id −*R* = Id −*RU* = $(P_U + P_{U^{\perp}}) - (P_U - P_{U^{\perp}}) = 2P_{U^{\perp}}$. (iii): ran (Id −*R*) = r an (2 P_{*U*⊥})</sub> = *D*[⊥] is closed. (iv): $(d - R)^{-1} = (2(d - P*U*))^{-1} = \frac{1}{2}Id + N_U$ ⊥. (v): We have

$$
T = P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}
$$

= $P_{D^{\perp}} \left(\frac{1}{2} \text{Id} + N_{U^{\perp}} \right) P_{U^{\perp}} - \frac{1}{2} P_{U^{\perp}}$
= $\frac{1}{2} P_{U^{\perp}} - \frac{1}{2} P_{U^{\perp}}$
= 0.

Example 5. *Let U be a closed subspace of X and suppose that*

$$
R = -R_U. \tag{29}
$$

Then

(i) $D = Fix(-R_U) = U^{\perp}$. (iii) Id −*R* = 2 P_{*U*}. (iii) ran $(Id - R) = U$ *is closed.* (iv) $(\text{Id} - R)^{-1} = \frac{1}{2} \text{Id} + N_U.$ (v) *T* = 0*.*

Proof. (i): Note that $-R_U = R_{U^{\perp}}$ and we learn from Example 4 that $D = Fix R = U^{\perp}$. (ii): $\mathop{\rm Id}\nolimits - R = \mathop{\rm Id}\nolimits - R_{U^{\perp}} = \bigl(P_U + P_{U^{\perp}} \bigr) - \bigl(2 P_{U^{\perp}} - \mathop{\rm Id}\nolimits \bigr) = \bigl(P_U + P_{U^{\perp}} \bigr) - \bigl(P_{U^{\perp}} - P_U \bigr) = 2 P_U.$ (iii): By using (ii), we have ran $(\text{Id} - R) = \text{ran } (2P_U) = D = U$. (iv): $(\text{Id} - R)^{-1} =$

■

REFERENCES 3674

 $\left(\mathrm{Id} - (R_{U^{\perp}})\right)^{-1} = \left(\mathrm{Id} - (2 P_{U^{\perp}} - \mathrm{Id})\right)^{-1} = \left(2(\mathrm{Id} - P_{U^{\perp}})\right)^{-1} = \frac{1}{2}\mathrm{Id} + N_U$ by [4, Example]. (v): By using (8), we have

$$
T = P_{D^{\perp}} (\text{Id} - R)^{-1} P_{D^{\perp}} - \frac{1}{2} P_{D^{\perp}}
$$

= $P_{D^{\perp}} \left(\frac{1}{2} \text{Id} + N_{U} \right) P_{U^{\perp}} - \frac{1}{2} P_{U^{\perp}}$
= $\frac{1}{2} P_{U^{\perp}} - \frac{1}{2} P_{U^{\perp}}$
= 0.

Acknowledgements

The author expresses gratitude to the reviewers for their insightful comments and constructive feedback, which greatly contributed to enhancing the quality of the work.

Clarification

Please note that a preprint has previously been published in arXiv and available in [3]. There is no conflict of interest and there is no data were used to support this study.

References

- [1] Salihah Alwadani, Heinz H Bauschke, Julian P Revalski, and Xianfu Wang. Resolvents and yosida approximations of displacement mappings of isometries. *Set-Valued and Variational Analysis*, 29:721–733, 2021.
- [2] Salihah Thabet Alwadani. *On the behaviour of algorithms featuring compositions of projectors and proximal mappings with no solutions*. PhD thesis, University of British Columbia, 2021.
- [3] Salihah Thabet Alwadani. Additional studies on displacement mapping with restrictions. *arXiv preprint arXiv:2405.13510*, 2024.
- [4] Heinz H Bauschke, Patrick L Combettes, Heinz H Bauschke, and Patrick L Combettes. *Correction to: convex analysis and monotone operator theory in Hilbert spaces*. Springer, 2017.
- [5] Heinz H Bauschke, Warren L Hare, and Walaa M Moursi. On the range of the douglas–rachford operator. *Mathematics of Operations Research*, 41(3):884–897, 2016.

- [6] Heinz H Bauschke, Victoria Martín-Márquez, Sarah M Moffat, and Xianfu Wang. Compositions and convex combinations of asymptotically regular firmly nonexpansive mappings are also asymptotically regular. *Fixed Point Theory and Applications*, 2012:1–11, 2012.
- [7] Heinz H Bauschke and Walaa M Moursi. On the order of the operators in the douglas–rachford algorithm. *Optimization Letters*, 10:447–455, 2016.
- [8] Heinz H Bauschke and Walaa M Moursi. The magnitude of the minimal displacement vector for compositions and convex combinations of firmly nonexpansive mappings. *Optimization Letters*, 12:1465–1474, 2018.
- [9] Heinz H Bauschke, Xianfu Wang, and Liangjin Yao. On borwein–wiersma decompositions of monotone linear relations. *SIAM Journal on Optimization*, 20(5):2636–2652, 2010.
- [10] Imtiyaz Ahmad Bhat, Lakshmi Narayan Mishra, Vishnu Narayan Mishra, and Cemil Tunc. Analysis of efficient discretization technique for nonlinear integral equations of hammerstein type. *International Journal of Numerical Methods for Heat & Fluid Flow*, 2024.
- [11] Regina S Burachik, Alfredo N Iusem, Regina S Burachik, and Alfredo N Iusem. *Enlargements of monotone operators*. Springer, 2008.
- [12] John B Conway. *A course in functional analysis*, volume 96. Springer, 2019.
- [13] Frank Deutsch and F Deutsch. *Best approximation in inner product spaces*, volume 7. Springer, 2001.
- [14] Jonathan Eckstein and Dimitri P Bertsekas. On the douglas—rachford splitting method and the proximal point algorithm for maximal monotone operators. *Mathematical programming*, 55:293–318, 1992.
- [15] Mohammed Sumebo Hogeme, Mesfin Mekuria Woldaregay, Laxmi Rathour, and Vishnu Narayan Mishra. A stable numerical method for singularly perturbed fredholm integro differential equation using exponentially fitted difference method. *Journal of Computational and Applied Mathematics*, 441:115709, 2024.
- [16] Robert E Megginson. *A course in functional analysis*.
- [17] Naol Tufa Negero, Gemechis File Duressa, Laxmi Rathour, and Vishnu Narayan Mishra. A novel fitted numerical scheme for singularly perturbed delay parabolic problems with two small parameters. *Partial Differential Equations in Applied Mathematics*, 8:100546, 2023.
- [18] R Tyrrell Rockafellar and Roger J-B Wets. *Springer-Verlag, corrected 3rd printing*, 2009.
- [19] MK Sharma, Nitesh Dhiman, Shubham Kumar, Laxmi Rathour, Vishnu Narayan Mishra, et al. Neutrosophic monte carlo simulation approach for decision making in medical diagnostic process under uncertain environment. *Int J Neutrosophic Sci*, 22(1):08–16, 2023.
- [20] Stephen Simons. *Minimax and monotonicity*. Springer, 2006.
- [21] Stephen Simons and F Takens. *From Hahn-Banach to Monotonicity*, volume 1693. Springer, 2008.
- [22] Eberhard Zeidler. *Nonlinear functional analysis and its applications: II/B: nonlinear monotone operators*. Springer Science & Business Media, 2013.
- [23] Eberhard Zeidler. *Nonlinear functional analysis and its applications: III: variational methods and optimization*. Springer Science & Business Media, 2013.